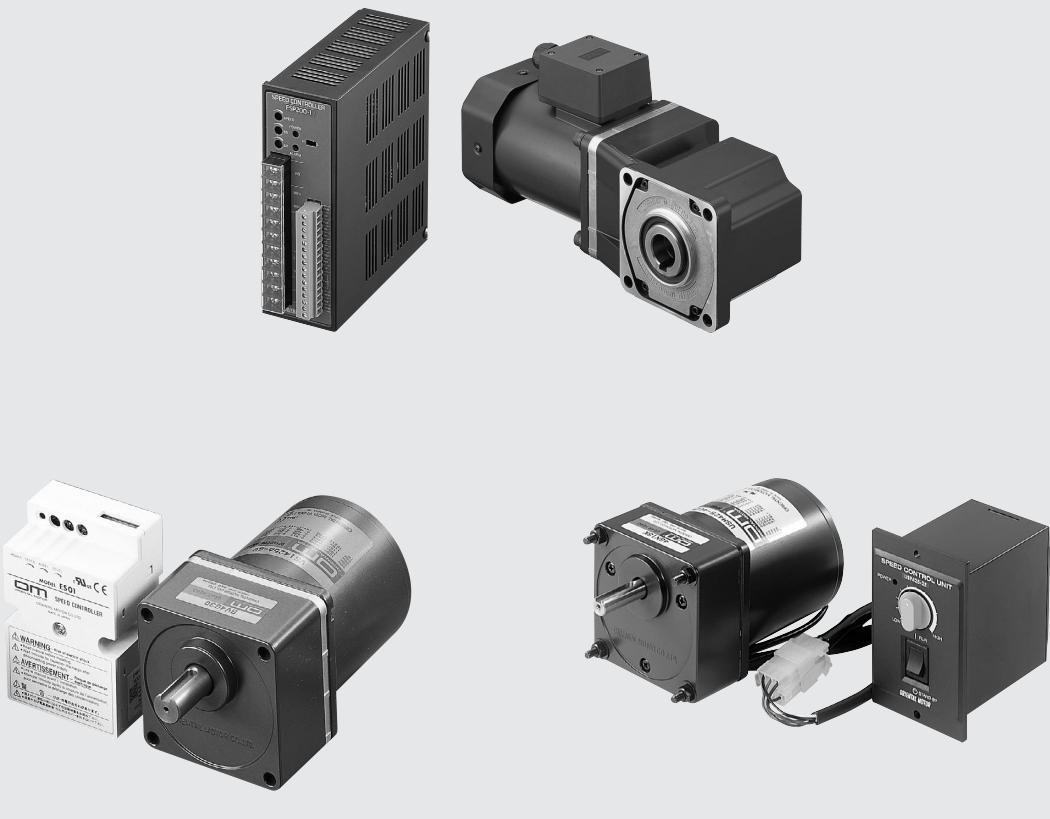


Speed Control Systems		Brushless DC Motor Systems		AC Motor Systems	
Introduction		AC Input	DC Input	AC Input	DC Input
BX		FBL II	AXU	AXH	BHF
					ES
					US



AC Motor Systems

Before Using a
Speed Control
System

Additional Information

- | | |
|--------------------------|-----|
| Technical Reference..... | F-1 |
| General Information..... | G-1 |

- | | |
|------------------|-------|
| BHF Series | B-70 |
| ES01/ES02 | B-86 |
| US Series | B-116 |

AC Motor Systems

BHF Series

200 W (1/4 HP)

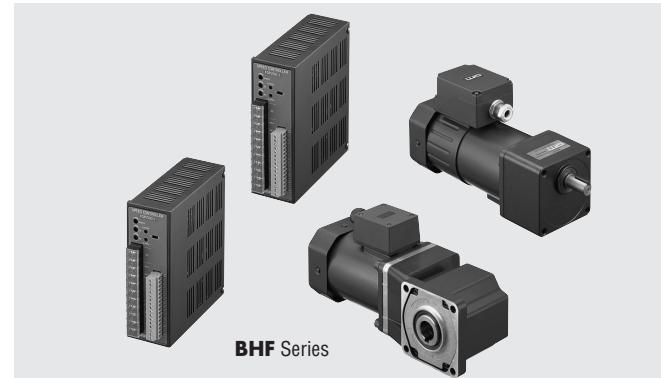
Frame Size: 4.09 in. sq. (104 mm sq.)

The **BHF** Series consists of a high-power 200 W (1/4 HP) AC speed-control motor combined with a dedicated inverter.

Each motor comes pre-assembled with a gearhead.

Combination Type (Pre-assembled Gearmotors)

The combination type (Pre-assembled Gearmotors) comes with the motor and its dedicated gearhead already assembled. This simplifies installation in equipment. Motors and gearheads are also available separately so they can be on hand to make changes or repairs.



Features

● Excellent speed stability

The combination of a dedicated inverter with a motor achieves excellent speed stability with a fluctuation of only $\pm 3\%$. The inverter is already optimized for use with the gearmotor, so detail adjustments are not required to achieve accurate speed control.

● Automatic control of an electromagnetic brake

The AC speed-control system with an electromagnetic brake allows automatic on/off control of the electromagnetic brake (power off activated type) on the inverter side. No longer will it be necessary to prepare a separate power supply or program a control sequence.

● Smallest frame size among 200 W (1/4 HP) motors

The **BHF** Series achieves an output of 200 W (1/4 HP), the highest among Oriental Motor's standard AC motors, with the smallest frame size [4.09 inch (104 mm) square] in that class. This allows for a reduction in the size of your equipment.

Safety Standards and CE Marking

	Standards	Certification Body	Standards File No.	CE Marking		
Motor	UL1004	UL	E64197	Low Voltage Directives / EMC Directives		
	UL2111					
	CSA C22.2 No.100					
	CSA C22.2 No.77					
	EN60950	Conforms to EN/IEC Standards				
	EN60034-1					
	EN60034-5					
	IEC60034-11					
	IEC60664-1					
Inverter	UL508C	UL	E171462			
	CSA C22.2 No.14					
	EN50178	Conforms to EN/IEC Standards				
	EN60950					

- When the system is approved under various safety standards, the model names on the motor and inverter nameplates are the approved model names.
- List of Motor Combinations** → Page B-85
- Details of Safety Standards** → Page G-2
- The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the motor/inverter incorporated in the user's equipment.

● Wiring length of up to 164 feet (50 m)

The wiring distance between the motor and inverter can be extended to a maximum of 164 feet (50 m).

● Full-range functionality

The **BHF** Series offers a variety of functions such as alarm output, speed monitor output and individual acceleration/deceleration setting. The driver also has a built-in I/O power supply.

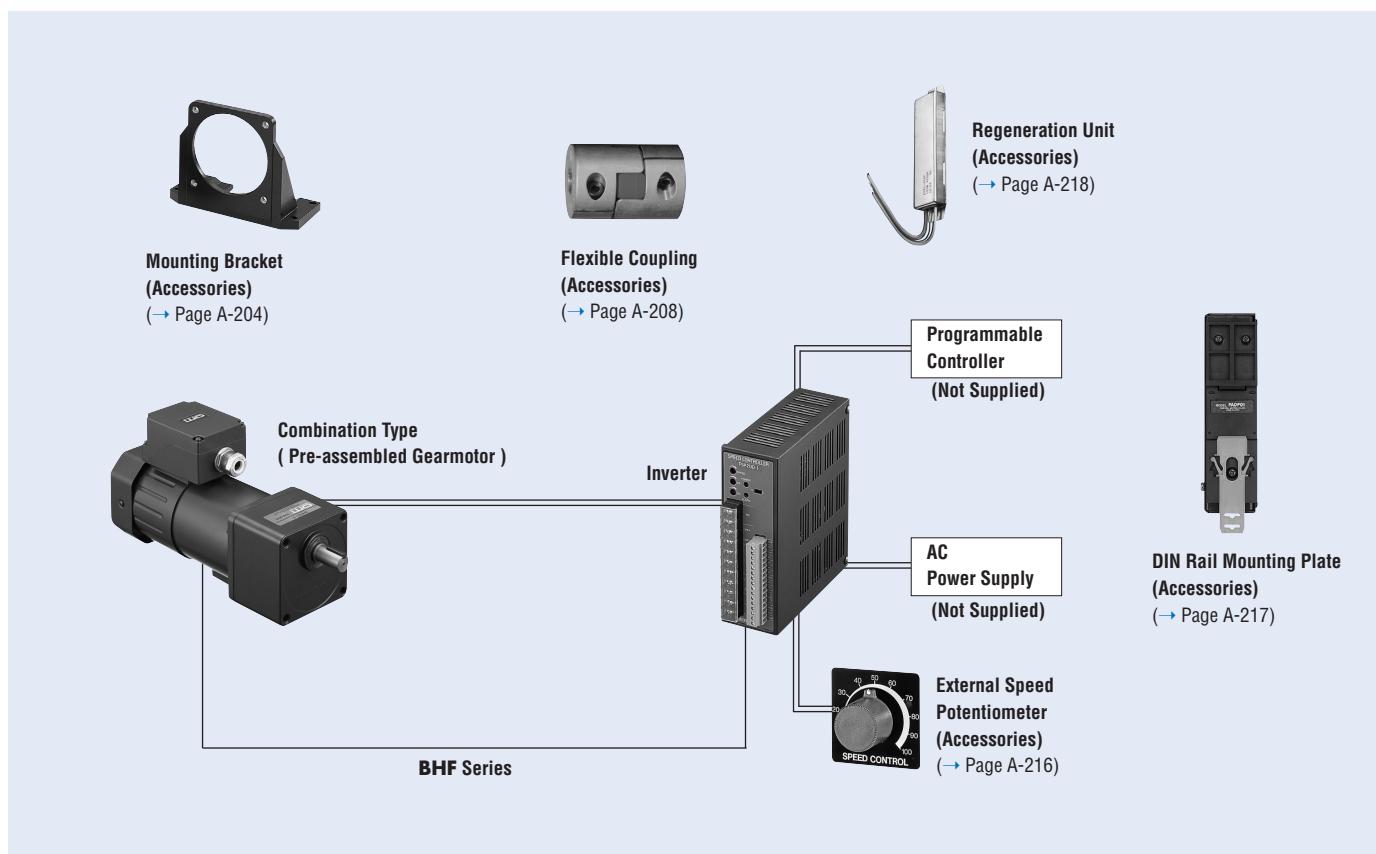
● Wide product variations

Pre-assembled gearmotors are available in a right-angle shaft type equipped with a hypoid gear (hollow shaft, solid shaft) and a parallel shaft type. A wide range of gear ratios are available. An electromagnetic brake type is also available.

● Global specifications

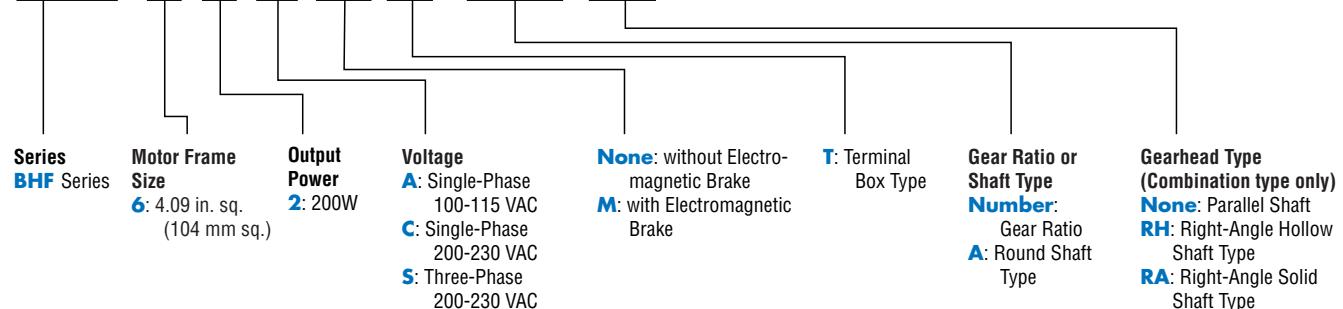
The **BHF** Series conforms to international power-supply voltage specifications, including single-phase 100-115 VAC, single-phase 200-230 VAC and three-phase 200-230 VAC. All units comply with the UL/CSA standards and bear the CE mark as proof of compliance with the Low Voltage Directive and EMC Directive.

■ System Configuration



■ Product Number Code

BHF 6 2 A M T- 100 RH



Product Line

Speed Control System Combination Type

Type	Power Supply Voltage	Model	Gear Ratio
Combination Type with Right-Angle Hollow Shaft	Single-Phase 100-115 VAC	BHF62AT-□RH	5~180
	Single-Phase 200-230 VAC	BHF62CT-□RH	5~180
	Three-Phase 200-230 VAC	BHF62ST-□RH	5~180
Combination Type with Right-Angle Solid Shaft	Single-Phase 100-115 VAC	BHF62AT-□RA	5~180
	Single-Phase 200-230 VAC	BHF62CT-□RA	5~180
	Three-Phase 200-230 VAC	BHF62ST-□RA	5~180
Combination Type with Parallel Shaft	Single-Phase 100-115 VAC	BHF62AT-□	3~180
	Single-Phase 200-230 VAC	BHF62CT-□	3~180
	Three-Phase 200-230 VAC	BHF62ST-□	3~180

- Enter the gear ratio in the box (□) within the model name.

Round Shaft Type

Type	Power Supply	Model
Round Shaft Type	Single-Phase 100-115 VAC	BHF62AT-A
	Single-Phase 200-230 VAC	BHF62CT-A
	Three-Phase 200-230 VAC	BHF62ST-A

Specifications

Speed Control System



Model	Combination Type	BHF62AT-□RH	BHF62CT-□RH	BHF62ST-□RH
		BHF62AT-□RA	BHF62CT-□RA	BHF62ST-□RA
Round Shaft Type		BHF62AT-A	BHF62CT-A	BHF62ST-A
Output Power	HP (W)		1/4 (200)	
Rated Speed	r/min		1500	
Rated Torque	oz-in (N·m)		180 (1.27)	
Starting Torque	oz-in (N·m)		180 (1.27)	
Permissible Torque	oz-in (N·m)		100~1500 r/min: 180 (1.27) 1800 r/min: 151 (1.07), 2400 r/min: 85 (0.6)	
Permissible Load Inertia J*	oz-in ² ($\times 10^{-4}$ kg·m ²)		44 (8)	
Speed Control Range	r/min		100~2400	
Power Source	Voltage	Single-Phase 100-115 VAC±10%	Single-Phase 200-230 VAC±10%	Three-Phase 200-230 VAC±10%
	Frequency		50 Hz/60 Hz	
	Rated Input Current	5.4 A	3.1 A	1.75 A
Speed Regulation	Max. Input Current	8.3 A	4.9 A	2.7 A
	Load		±3% Max. (0~Rated Torque, at 1500 r/min)	
	Voltage		±3% Max. (Power supply voltage ±10% at 1500 r/min with no load)	
Temperature			±3% Max. [32°F~122°F (0°C~+50°C) at 1500 r/min with no load]	

* The permissible load inertia specified above is only applicable for the round shaft types. Permissible Load Inertia for the Combination Types → Page B-75

• The values for each specification applies to the motor only.

• Enter the gear ratio in the box (□) within the model name.

Speed Control System with Electromagnetic Brake Combination Type

Type	Power Supply Voltage	Model	Gear Ratio
Combination Type with Right-Angle Hollow Shaft	Single-Phase 100-115 VAC	BHF62AMT-□RH	5~180
	Single-Phase 200-230 VAC	BHF62CMT-□RH	5~180
	Three-Phase 200-230 VAC	BHF62SMT-□RH	5~180
Combination Type with Right-Angle Solid Shaft	Single-Phase 100-115 VAC	BHF62AMT-□RA	5~180
	Single-Phase 200-230 VAC	BHF62CMT-□RA	5~180
	Three-Phase 200-230 VAC	BHF62SMT-□RA	5~180
Combination Type with Parallel Shaft	Single-Phase 100-115 VAC	BHF62AMT-□	3~180
	Single-Phase 200-230 VAC	BHF62CMT-□	3~180
	Three-Phase 200-230 VAC	BHF62SMT-□	3~180

- Enter the gear ratio in the box (□) within the model name.

Round Shaft Type

Type	Power Supply	Model
Round Shaft Type	Single-Phase 100-115 VAC	BHF62AMT-A
	Single-Phase 200-230 VAC	BHF62CMT-A
	Three-Phase 200-230 VAC	BHF62SMT-A

● Speed Control System with Electromagnetic Brake



Model	Combination Type	BHF62AMT-□RH BHF62AMT-□RA BHF62AMT-□	BHF62CMT-□RH BHF62CMT-□RA BHF62CMT-□	BHF62SMT-□RH BHF62SMT-□RA BHF62SMT-□
	Round Shaft Type	BHF62AMT-A	BHF62CMT-A	BHF62SMT-A
Output Power	HP (W)		1/4 (200)	
Rated Speed	r/min		1500	
Rated Torque	oz-in (N·m)		180 (1.27)	
Starting Torque	oz-in (N·m)		180 (1.27)	
Permissible Torque	oz-in (N·m)		100~1500 r/min: 180 (1.27) 1800 r/min: 151 (1.07), 2400 r/min: 85 (0.6)	
Permissible Load Inertia J*	oz-in ² ($\times 10^{-4}$ kg·m ²)		44 (8)	
Speed Control Range	r/min		100~2400	
Power Source	Voltage	Single-Phase 100-115 VAC±10%	Single-Phase 200-230 VAC±10%	Three-Phase 200-230 VAC±10%
	Frequency		50 Hz/60 Hz	
	Rated Input Current	5.4 A	3.1 A	1.75 A
	Max. Input Current	8.3 A	4.9 A	2.7 A
Speed Regulation	Load		±3% Max. (0~Rated Torque, at 1500 r/min)	
	Voltage		±3% Max. (Power supply voltage ±10% at 1500 r/min with no load)	
	Temperature		±3% Max. [32°F~122°F (0°C~+50°C) at 1500 r/min with no load]	
Electromagnetic Brake Holding Brake Torque	oz-in (N·m)		210 (1.5)	
Lowering Operation		Connecting the regeneration unit [Accessories (Sold Separately)], Max. output 100 W (5 minutes rating)		

* The permissible load inertia specified above is only applicable for the round shaft types. Permissible Load Inertia for the Combination Types → Page B-75

- The values for each specification applies to the motor only.
- Enter the gear ratio in the box (□) within the model name.

■ Common Specifications

● Speed Control System / Speed Control System with Electromagnetic Brake

Item	Specifications
Acceleration/Deceleration Time	0.1~25 seconds (at 1000 r/min)
Speed Control Method	Any one of the following methods: 1. By built-in potentiometer (1 piece) 2. By external potentiometer (20 kΩ 1/4 W) 3. By DC voltage control (0~5 VDC)
Input Signal	Photocoupler input Input impedance 2.4 kΩ Operates at 12 VDC Common to CW/CCW, Speed setting mode selection, Slow down, Alarm reset
Output Signal	Open collector output External use conditions 26.4 VDC, 10 mA max. Common to SPEED OUT (12P/R), ALARM OUT
Protection Functions	If any of the protective functions of the inverter are triggered, the ALM output will be turned off and the ALM LED on the front panel of the inverter will blink or turn on while the motor current is interrupted to stop the motor. <ul style="list-style-type: none"> • Overload protection: A load exceeding the rated torque has been applied to the motor for 5 seconds or more. • Overvoltage protection: The voltage applied to the inverter has exceeded the rated voltage by approximately 30% or more. • The motor is being operated beyond the lowering operation's ability. • Overcurrent protection: An excessive current is flowing within the inverter. • Undervoltage protection: The power-supply voltage has dropped below the rated voltage by approximately 15% or more. • Circuit overheat protection: The ambient operating temperature for the inverter has exceeded its upper limit. • Motor open circuit protection: The motor cable has an open circuit or improper connection. • EEPROM Error: An error was detected in the EEPROM.
Rating	Continuous
Motor Insulation Class	Class B (266°F [130°C])

General Specifications

Item	Motor	Inverter
Insulation Resistance	100 MΩ or more when measured by a 500 VDC megger between the windings and the frame after rated motor operation under normal ambient temperature and humidity.	100 MΩ or more when measured by a 500 VDC megger between the power supply input terminal and the Protective Earth terminal and between the power supply input terminal and the I/O terminal after continuous operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz and 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.	Sufficient to withstand 1.5 kV (3 kV) at 50 Hz and 60 Hz applied between the power supply input terminal and the Protective Earth terminal (between the power supply input terminal and the I/O terminal) for 1 minute after continuous operation under normal ambient temperature and humidity.
Temperature Rise	126°F (70°C) or less in the coil, as measured by the resistance change method after rated operation with gearhead or similar heat radiation plate* installed.	_____
Ambient Temperature	14°F~104°F (-10°C to +40°C) 14°F~122°F (-10°C to +50°C) for 100/200 VAC	32°F~122°F (0°C~+50°C) (nonfreezing)
Ambient Humidity	85% maximum (noncondensing)	85% maximum (noncondensing)
Degree of Protection	IP54 (excluding the motor-installation surface of the round shaft type)	IP10

* Size of heat radiation plate: 9.06 inch × 9.06 inch (230 mm × 230 mm), 0.20 inch (5 mm) in thickness (material: aluminum)

Permissible Torque for Combination Type

Right-Angle Shaft

Unit = Upper values: lb-in/Lower values: N·m

Model	Gear Ratio Motor Output Speed	5	9	15	30	50	100	180
		100~1500 r/min	40	73	123	240	350	480
BHF62AT-□RH/RA, BHF62AMT-□RH/RA	4.6	8.3	13.9	27.8	40	54.5	60	60
BHF62CT-□RH/RA, BHF62CMT-□RH/RA	3.9	61	103	200	320	480	530	530
BHF62ST-□RH/RA, BHF62SMT-□RH/RA	1800 r/min	7	11.7	23.4	37	54.5	60	60
	2400 r/min	19.4	34	58	115	193	380	530
		2.2	3.9	6.6	13.1	21.9	43	60

- Enter the gear ratio in the box (□) within the model name.
- Direction of rotation of the motor and that of the gear output shaft are the opposite.

Parallel Shaft

Unit = Upper values: lb-in/Lower values: N·m

Model	Gear Ratio Motor Output Speed	3	5	9	15	30	50	100	180
		100~1500 r/min	30	50	91	145	290	350	350
BHF62AT-□, BHF62AMT-□	3.4	5.7	10.3	16.4	32.8	40	40	40	40
BHF62CT-□, BHF62CMT-□	1800 r/min	25	42	76	122	240	350	350	350
BHF62ST-□, BHF62SMT-□	2.9	4.8	8.7	13.8	27.6	40	40	40	40
	2400 r/min	14.1	23	43	68	137	210	350	350
		1.6	2.7	4.9	7.7	15.5	24.3	40	40

- Enter the gear ratio in the box (□) within the model name.
- A colored background indicates gear shaft rotation in the same direction as the motor shaft; a white background indicates rotation in the opposite direction.

Permissible Overhung Load and Permissible Thrust Load

The overhung load and thrust load of the gearhead's output shaft affect the bearing life. Make sure the overhung load and thrust load do not exceed the values shown in the table below.

Model	Gear Ratio	Permissible Overhung Load [lb. (N)]		Permissible Thrust Load lb. (N)
		from the tip of the shaft 0.39 inch (10 mm)	from the tip of the shaft 0.79 inch (20 mm)	
BHF62□T-□RH	5~30	270 (1200)	240 (1100)	
BHF62□MT-□RH	50~180	490 (2200)	450 (2000)	67 (300)
BHF62□T-□RA	5~30	200 (900)	220 (1000)	
BHF62□MT-□RA	50~180	380 (1700)	410 (1850)	67 (300)
BHF62□T-□	3~30	123 (550)	180 (800)	
BHF62□MT-□	50~180	146 (650)	220 (1000)	45 (200)

- With the hollow shaft type, the permissible overhung load is measured from the flange-mounting surface.
- Enter the voltage (A, C, S) in the box (□).
- Enter the gear ratio in the box (□) within the model name.
- Permissible Overhung Load and Thrust Load for Round Shaft Type → Page A-11

■ Permissible Load Inertia J for the Combination Type

Unit = Upper values: oz-in²/Lower values: ×10⁻⁴ kg·m²

Model	\	Gear Ratio	3	5	9	15	30	50	100	180
BHF62	T-□RH, BHF62	T-□RA								
BHF62	MT-□RH, BHF62	MT-□RA								
BHF62	T-□		98	270	880	2400	9800	27000	27000	27000
BHF62	MT-□		18	50	162	450	1800	5000	5000	5000
BHF62	MT-□									

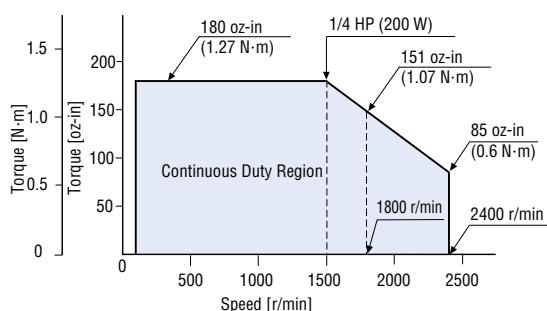
- Enter the voltage (A, C, S) in the box (□).
- Enter the gear ratio in the box (□) within the model name.

■ Speed — Torque Characteristics

The characteristics shown below are only applicable for the motors only.

Continuous Duty Region: Continuous operation is possible in this region.

Common to **BHF** Series

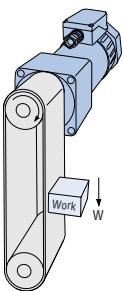


■ Vertical Drive (Gravitational Operation)

The **BHF** Series achieves stable speed control during gravitational operation.

During vertical movement (gravitational operation), such as the application illustrated below, normally an external force causes the motor to rotate and function as a power generator. If this energy is applied to the inverter, an error will occur. A regeneration unit (sold separately) can convert regenerative energy into thermal energy for dissipation. Use the optional regeneration unit **EPRC-400P** when using the motor for vertical drive applications or when braking a large inertial load quickly.

Regenerative power: 100 W (5-minute rating)
Instantaneous regenerative power: 300 W



● Regenerative power

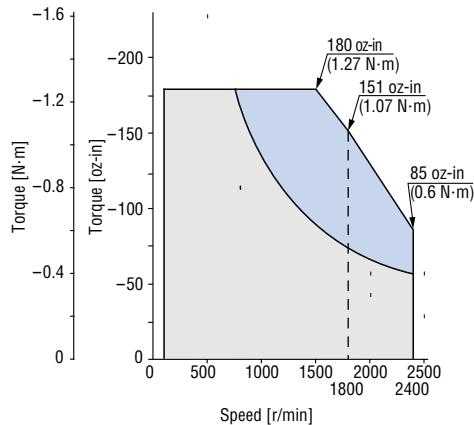
The regenerative power may be calculated roughly using the equation shown below for reference.

$$\text{Regenerative power (W)} = 0.1047 \times T_L [\text{N} \cdot \text{m}] \times N [\text{r}/\text{min}]$$

T_L: Load torque N: Speed

* Use the electromagnetic-brake type for gravitational operation.

● Gravitational operation ability



Use the time shown below as a guideline when performing continuous gravitational operation:



Operating range in which regenerative power is 100 W or less
Allowable time for continuous gravitational operation: 1 minute, 30% ED



Operating range in which regenerative power exceeds 100 W
Allowable time for continuous gravitational operation: 1 minute, 20% ED

Example: 1 minute, 30%

Under gravitational operation: 60 seconds*

Non-gravitational operation: 140 seconds

* 60 seconds (1 minute) is the maximum continuous gravitational operation time allowed.

Dimensions Scale 1/4, Unit = inch (mm)

Mounting screws are included with combination type motor. → Page B-133

Enter the gear ratio in the box (□) within the model name.

● Motor/Gearhead (Combination Type with Right-Angle Hollow Shaft)

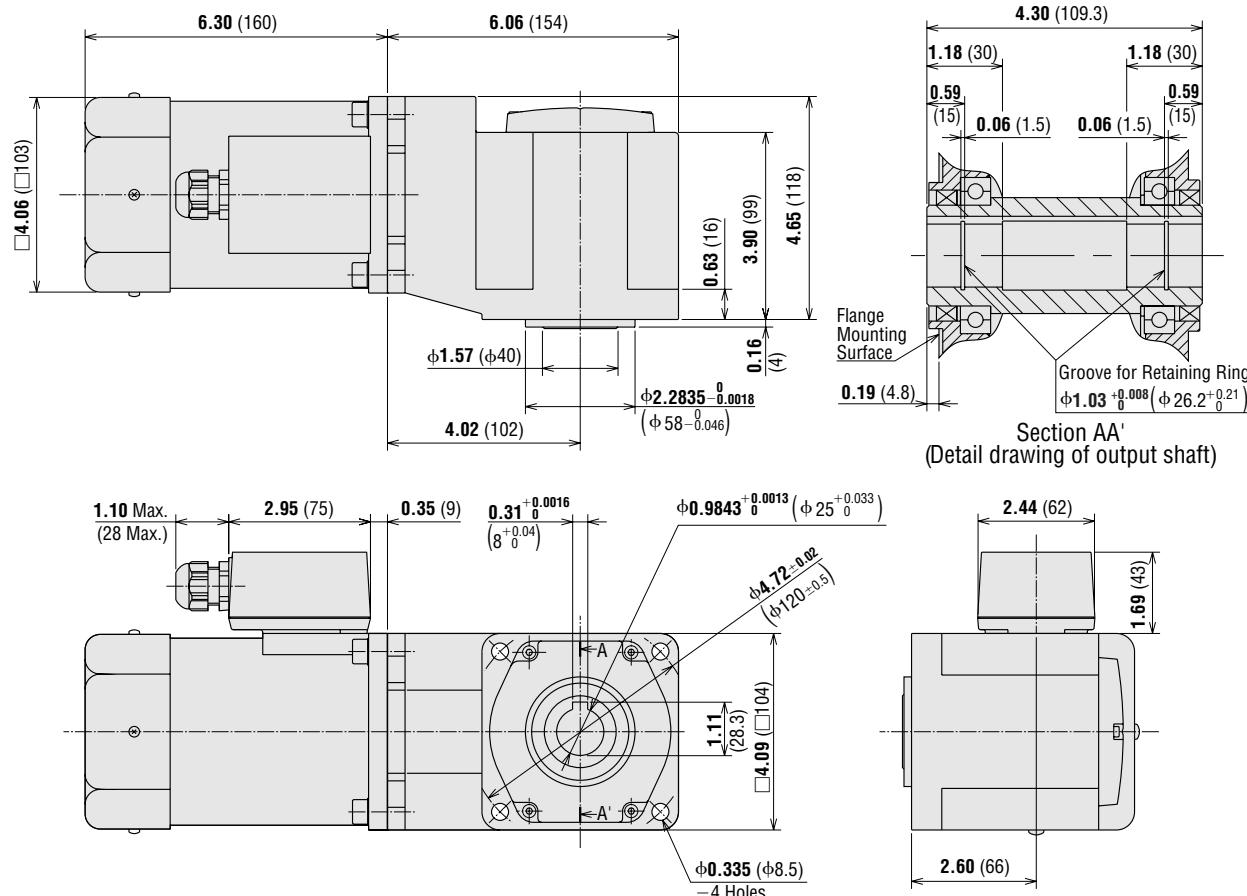
BHF62AT-□RH, BHF62CT-□RH, BHF62ST-□RH

Motor Model: BHM62T-G2

Gearhead Model: BHG62-□RH

Weight: 22 lb. (10.0 kg)

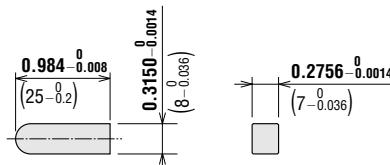
DXF A301



● Use cable (VCTF) with a diameter of $\phi 0.24$ inch ($\phi 6$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).

● Details of Terminal Box → Page A-224

● Key (Included) (Scale 1/2)



Introduction	BX	FBL II	AXU	AXH	BHF	ES	US	AC Motor Systems
Brushless DC Motor Systems	AC Input	DC Input						AC Motor Systems
								Before using a Speed Control System

● Motor/Gearhead (Combination Type with Right-Angle Solid Shaft)

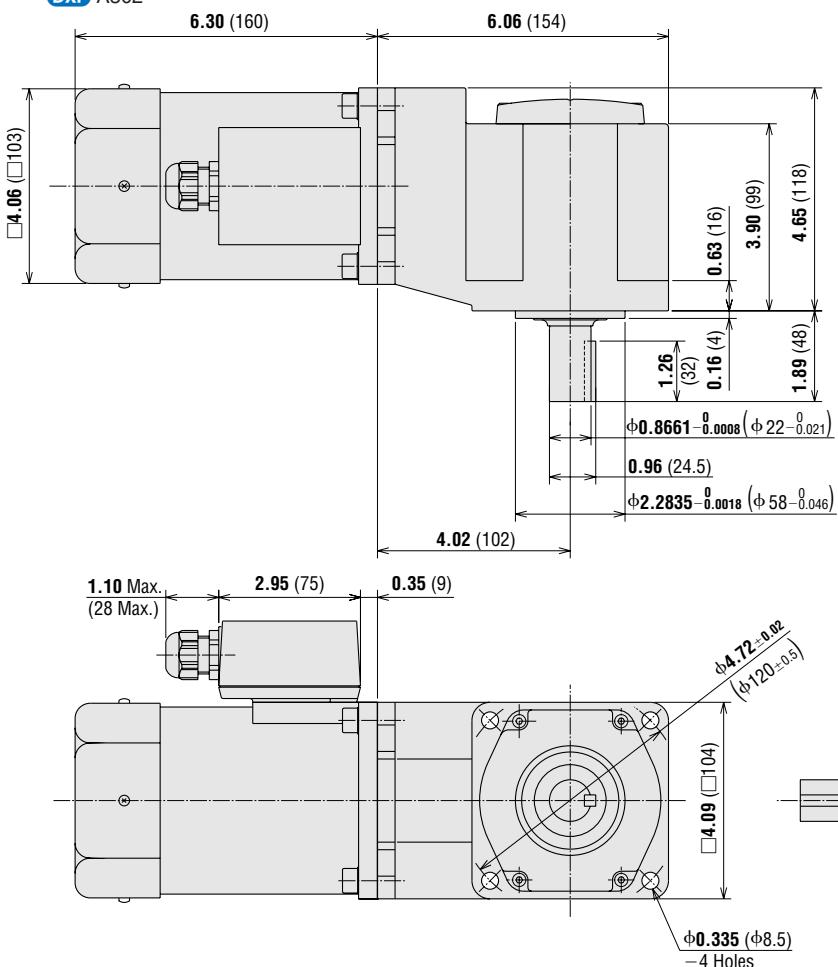
BHF62AT-□RA, BHF62CT-□RA, BHF62ST-□RA

Motor Model: BHM62T-G2

Gearhead Model: BHG6G2-□RA

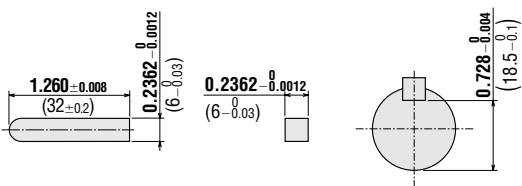
Weight: 22 lb. (10.0 kg)

DXF A302



● Key and Key Slot (Included) (Scale 1/2)

At the time of shipment, the parallel key is pressed into the key slot.



- Use cable (VCTF) with a diameter of $\phi 0.24$ inch ($\phi 6$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).
- Details of Terminal Box → Page A-224

● Motor/Gearhead (Combination Type with Parallel Shaft)

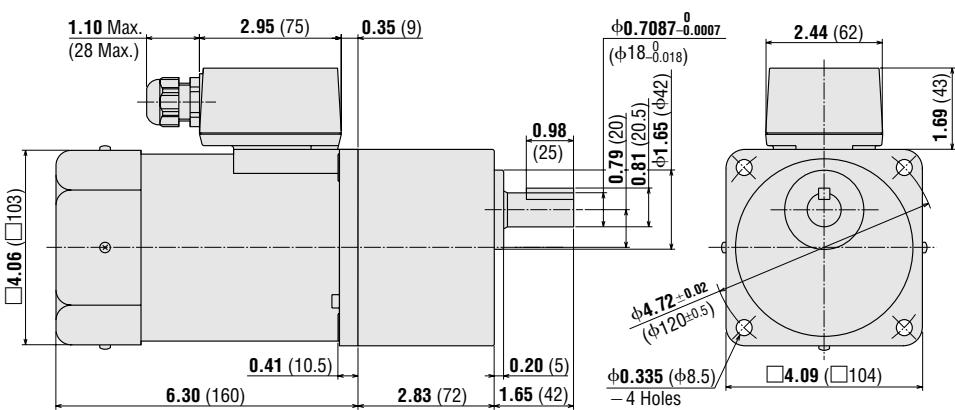
BHF62AT-□, BHF62CT-□, BHF62ST-□

Motor Model: BHM62T-G2

Gearhead Model: BHG6G2-□

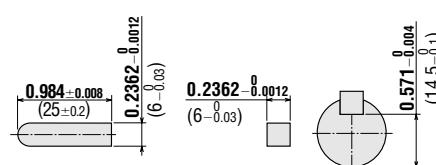
Weight: 17.6 lb. (8.0 kg)

DXF A304



● Key and Key Slot (Included) (Scale 1/2)

At the time of shipment, the parallel key is pressed into the key slot.



- Use cable (VCTF) with a diameter of $\phi 0.24$ inch ($\phi 6$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).
- Details of Terminal Box → Page A-224

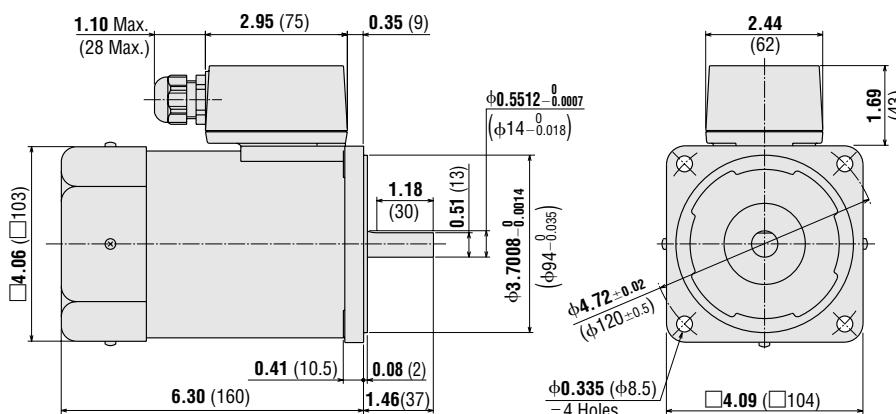
● Round Shaft Type

BHF62AT-A, BHF62CT-A, BHF62ST-A

Motor Model: BHM62T-A

Weight: 11 lb. (5.0 kg)

DXF A308



● Use cable (VCTF) with a diameter of $\phi 0.24$ inch ($\phi 6$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).

● Details of Terminal Box → Page A-224

● Motor/Gearhead (Combination Type with Right-Angle Hollow Shaft)

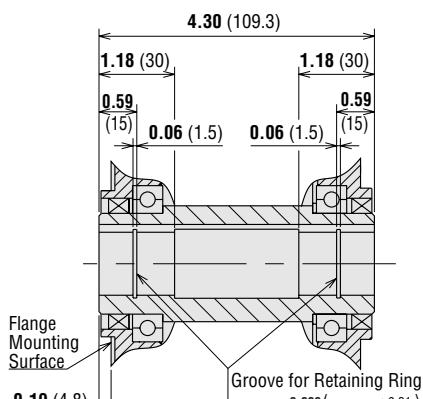
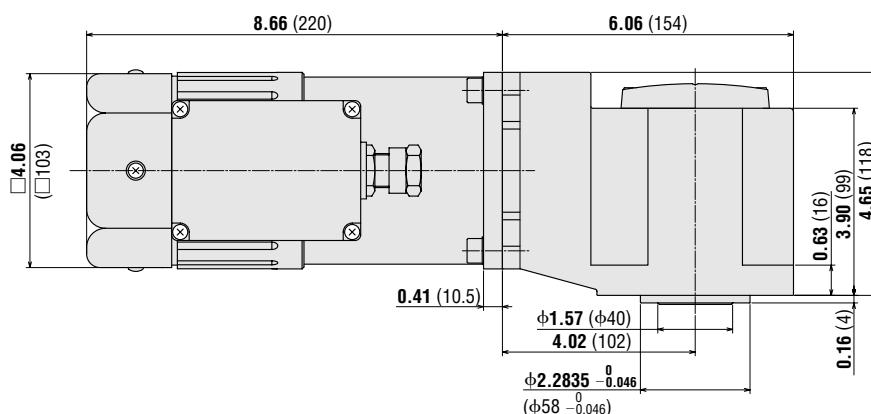
BHF62AMT-□RH, BHF62CMT-□RH, BHF62SMT-□RH

Motor Model: BHM62MT-G2

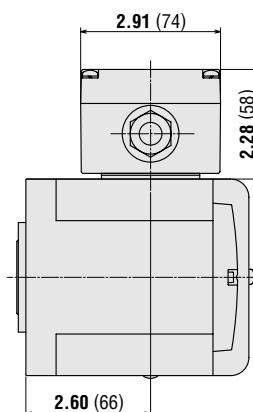
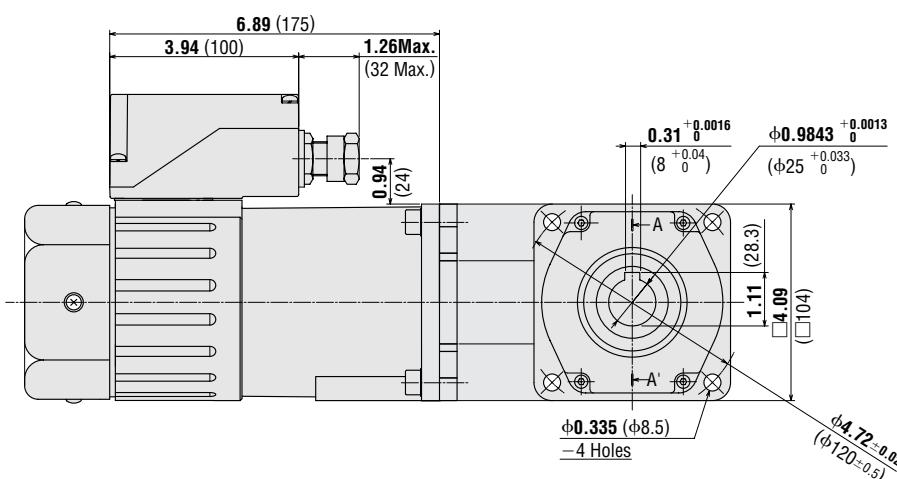
Gearhead Model: BHG62-□RH

Weight: 25.3 lb. (11.5 kg)

DXF A384

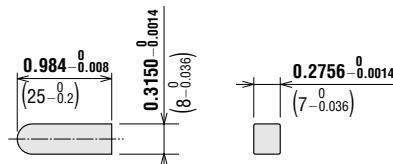


Section AA'
(Detail drawing of output shaft)



● Use cable (VCTF) with a diameter of $\phi 0.32$ inch ($\phi 8$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).

● Key (Included) (Scale 1/2)



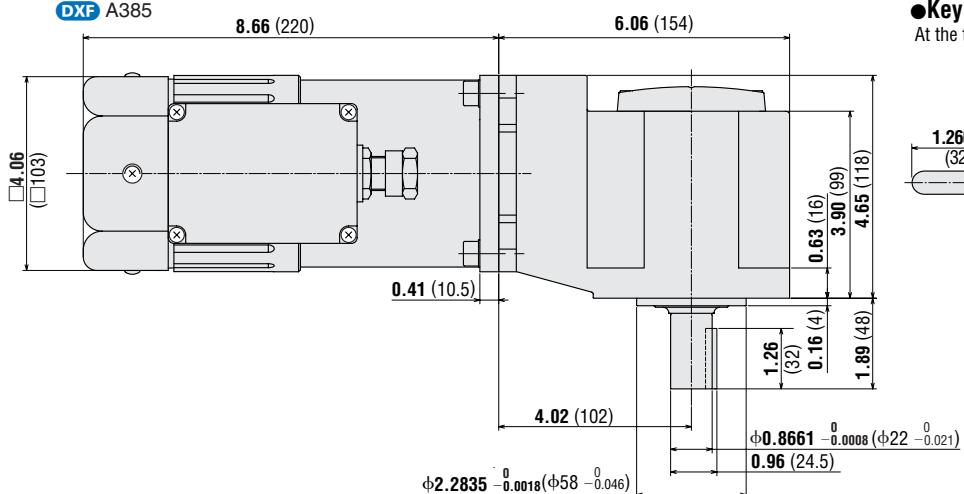
● Motor/Gearhead (Combination Type with Right-Angle Solid Shaft)
BHF62AMT-□RA, BHF62CMT-□RA, BHF62SMT-□RA

Motor Model: BHM62MT-G2

Gearhead Model: BHG62-□RA

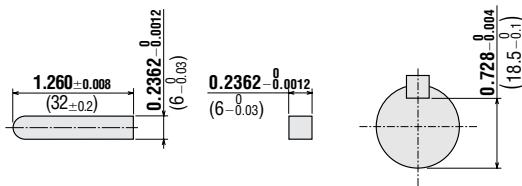
Weight: 25.3 lb. (11.5 kg)

DXF A385



● Key and Key Slot (Included) (Scale 1/2)

At the time of shipment, the parallel key is pressed into the key slot.



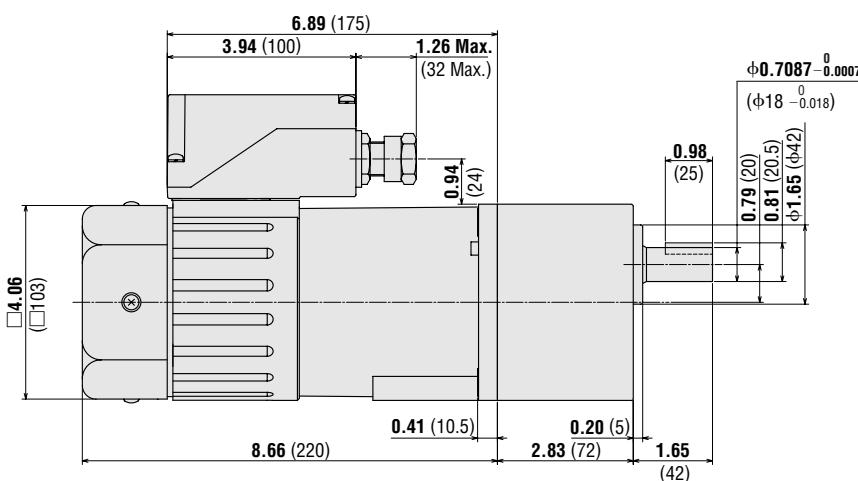
● Motor/Gearhead (Combination Type with Parallel Shaft)
BHF62AMT-□, BHF62CMT-□, BHF62SMT-□

Motor Model: BHM62MT-G2

Gearhead Model: BHG62-□

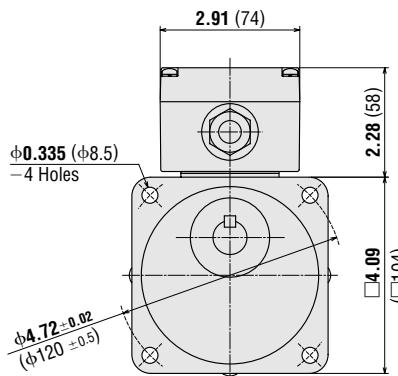
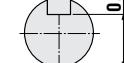
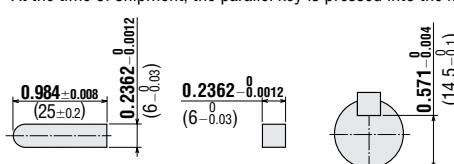
Weight: 20.9 lb. (9.5 kg)

DXF A386



● Key and Key Slot (Included) (Scale 1/2)

At the time of shipment, the parallel key is pressed into the key slot.



● Use cable (VCTF) with a diameter of $\phi 0.32$ inch ($\phi 8$ mm)~ $\phi 0.47$ inch ($\phi 12$ mm).

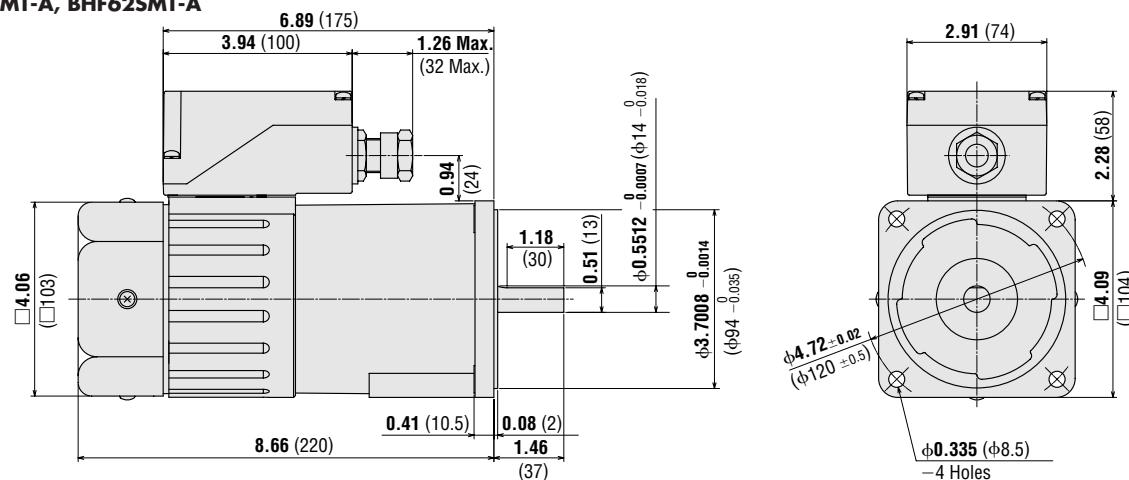
● Round Shaft Type

BHF62AMT-A, BHF62CMT-A, BHF62SMT-A

Motor Model: BHM62MT-A

Weight: 14.3 lb. (6.5 kg)

DXF A387



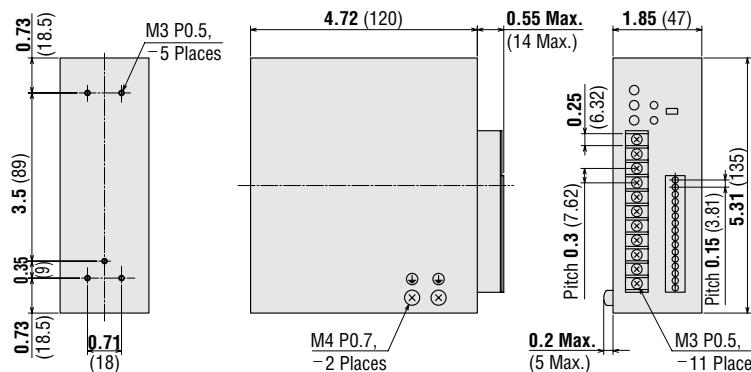
● Use cable (VCTF) with a diameter of Ø 0.32 inch (Ø 8 mm)~Ø 0.47 inch (Ø 12 mm).

● Inverter

FSP200-1, FSP200-2, FSP200-3

Weight: 1.32 lb. (0.6 kg)

DXF A390

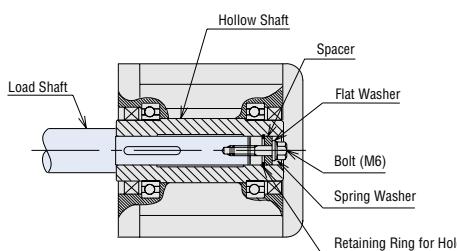


■ Mounting Method for Hollow Shaft Gearheads

These diagrams show how to mount loads depending on the shape of the shaft.

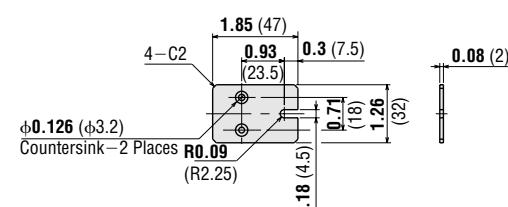
The tolerance of the inner diameter for the hollow shaft is finished as H8, and "key slot" processing is given to mount the load shaft. The recommended tolerance of the load shaft is h7. Use the key provided with the product by fastening it to the shaft. Apply a coating of molybdenum disulfide or similar grease to the inner diameter of the load shaft to prevent binding. Recommended load shaft dimensions are shown to the right.

● Stepped-Down Shaft



● Mounting Tab

(1 set of 2 pieces included)



Recommended size of inner diameter for the hollow shaft and load shaft

Unit=inch (mm)

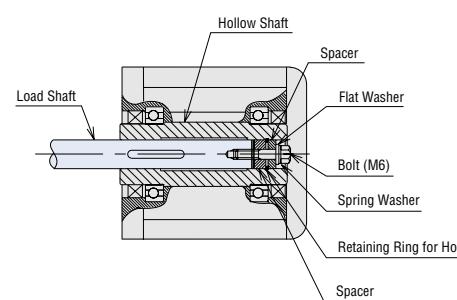
Model	BH6G2-□RH
Inner diameter of hollow shaft H8	$\phi 0.9843^+_{-0} \text{ (Ø} 25^+_{-0} \text{ mm)}$
Recommended load shaft diameter h7	$\phi 0.9843^0_{-0.0008} \text{ (Ø} 25^0_{-0.021} \text{ mm)}$

● Replace the safety cover after installing the load shaft.

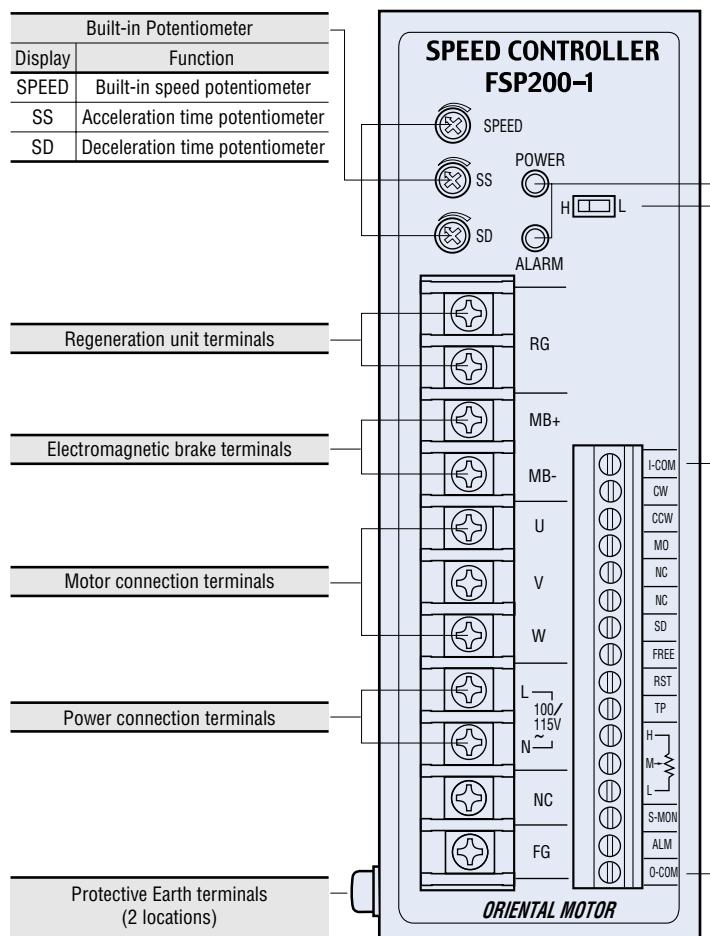
Note:

● Be careful not to apply a shock to the hollow shaft when mounting a load. It may damage the bearing inside the gearhead.

● Straight Load Shaft



■ Connection and Operation



The unit shown above uses a single-phase 100/115 V power-supply input.

LED Display		
Display	Function	Lighting Condition
POWER	Power indicator	Turns on (green) while power is being supplied.
ALARM	Alarm indicator	Turns on (red) or blinks when an alarm is triggered.

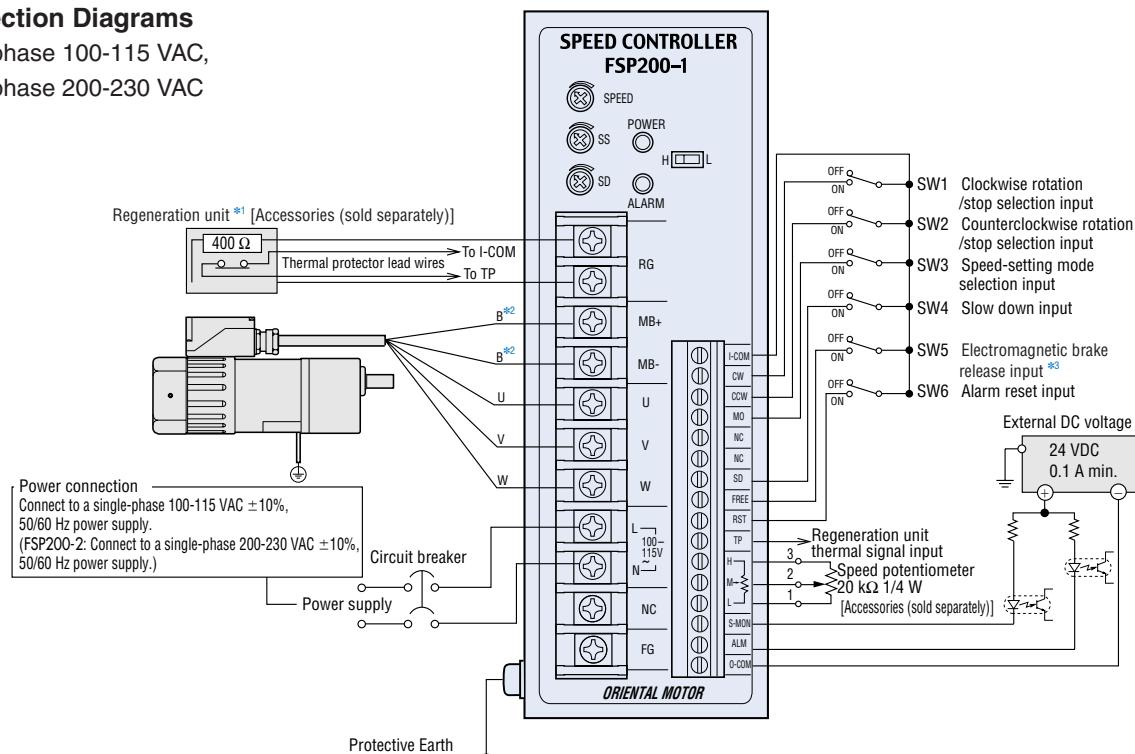
Switch

Set the switch to "H" if the cable between the motor and inverter is less than 32.8 ft. (10 m) in length. Set it to "L" if the cable length exceeds 32.8 ft. (10 m).

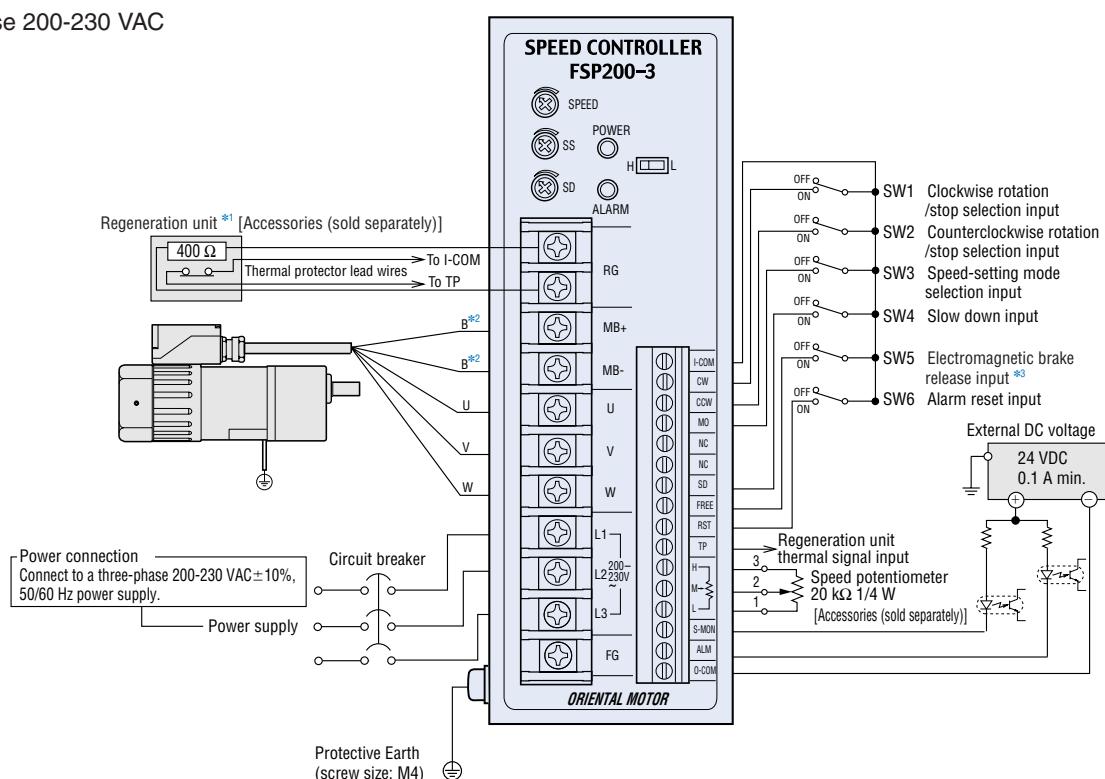
Input/Output Signal Terminals Block		
Display	Signal	Function and Operation
IN-COM	Ground terminal for input signals	Ground terminal for input signals.
CW	Clockwise rotation input	Clockwise rotation/stop selection input
CCW	Counterclockwise rotation input	Counterclockwise rotation/stop selection input
MO	Speed-setting mode selection input	Built-in/external speed-setting selection input
NC	—	—
NC	—	—
SD	Slow down input	Instantaneous stop/slow down stop selection input
FREE	Electromagnetic brake release input	Electromagnetic brake releases/locks selection input
RST	Alarm reset input	This input is used to reset the alarm while in an energized state in the event any protective function of the inverter is activated.
TP	Thermal signal input	This input is used to connect the lead wire of the regeneration unit's internal thermal protector when the braking regeneration unit (sold separately) is used.
H, M, L	Speed-setting mode selection input	These are connected for speed control via the external speed potentiometer or external DC voltage.
S-MON	Speed monitor output	This output is used to monitor the motor speed. Pulse signals at a rate of 12 pulses per revolution of the motor output shaft.
ALM	Alarm output	When the protective function is activated, this output is set to OFF ("H") and the motor stops.
O-COM	Ground terminal for output signals	Ground terminal for output signals.

● Connection Diagrams

- ◆ Single-phase 100-115 VAC,
Single-phase 200-230 VAC



- ◆ Three-phase 200-230 VAC



See page A-215 for connection of the **SDM496** speed indicator.

*1 This should be connected only when using a regeneration unit.

*2 This should be connected only for a speed control system with an electromagnetic brake.

*3 The electromagnetic brake release input can be used only with a speed control system with electromagnetic brake.

Notes:

- If the wiring between the motor and inverter needs to be extended by 32.8 ft. (10 m) or more, use a polyethylene-insulated electric wire of AWG16 or larger. Do not connect more than one cable or allow the overall wiring length to exceed 164 ft. (50 m). Doing so may result in a malfunction.
- With the electromagnetic brake type, setting the wiring length too long delays the operation of the electromagnetic brake [by approx. 100 ms at a wiring length of 164 ft. (50 m)]. To minimize the delay time, use separate cables for the electromagnetic brake cable and motor cable.
- Separate the signal and motor cables from noise-generating equipment or power lines.
- After connecting each cable to the terminal block, be sure to install the connector cover.

Connecting the motor and inverter

A motor cable is not supplied with the product. Please provide the appropriate cable.

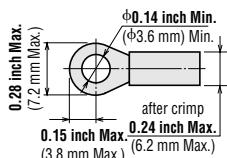
● Connecting the Motor

Appropriate lead wires

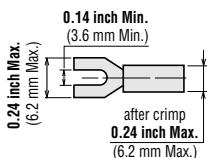
AWG 18 min.

Terminals (Use a crimp terminal for the electromagnetic brake type.)

Round Terminal with Insulation

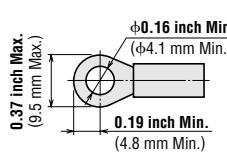


U-Shape Terminal with Insulation



Protective Earth

Round Terminal with Insulation



● Connecting the Inverter

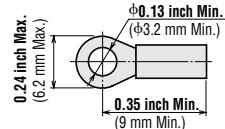
Power input terminals, motor connection terminals

Appropriate lead wires

AWG 18 min.

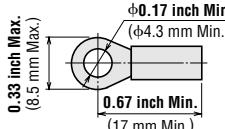
Terminals

Round Terminal with Insulation



Protective Earth

Round Terminal with Insulation



I/O signal terminal

When a crimp terminal should be used, use one of the following terminals:

Phoenix Contact

AI 0.25-6

Applicable wiring gauge: AWG 24

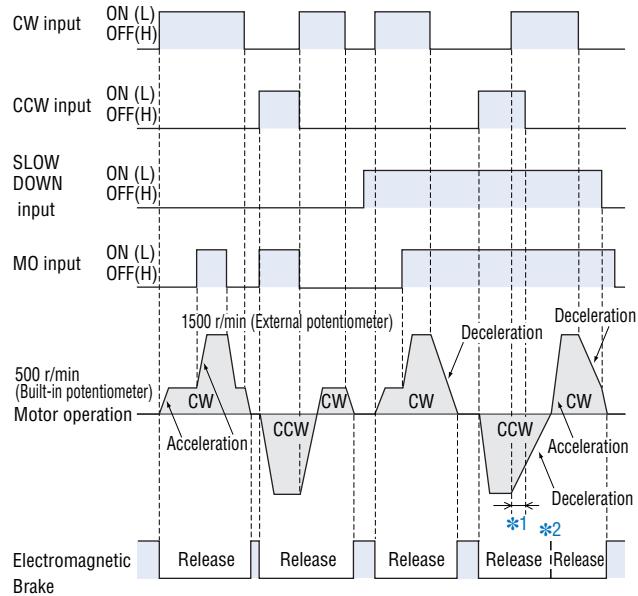
AI 0.34-6

Applicable wiring gauge: AWG 22

AI 0.5-6

Applicable wiring gauge: AWG 20

● Timing Chart



*1 The motor will stop if the CW and CCW inputs are simultaneously turned to ON ("L" level).

*2 When the motor runs and/or stops in a short cycle, the electromagnetic brake may be left released if a shorter time is set for the acceleration/deceleration time.

- All run, stop, direction change and speed change operations can be controlled by the CW, CCW, M0, and SD input signals.
- If the CW input is set to ON ("L" level), the motor rotates in a clockwise direction as viewed from the shaft end of the motor; if the CW input is set to OFF ("H" level), the motor stops. If the CCW input is set to ON ("L" level), the motor rotates in a counterclockwise direction as viewed from the shaft end of the motor; if the CCW input is set to OFF ("H" level), the motor stops. The acceleration time is set by the built-in acceleration potentiometer (SS).
- If the SD input is set to ON ("L" level), the deceleration time is the value set by the built-in deceleration potentiometer (SD).
- Turning the M0 input to ON ("L" level) selects the speed set by the external speed potentiometer. Turning the input to OFF ("H" level) causes the motor to operate at the speed set by the built-in speed potentiometer. The timing chart shown at left is based on a built-in speed-potentiometer setting of 500 r/min and an external speed-potentiometer setting of 1500 r/min.
- To release the electromagnetic brake when the motor is stopped, turn the FREE (electromagnetic brake release) input to ON ("L" level). This releases the electromagnetic brake and allows the motor's output shaft to turn freely. (This function is available only with a speed control system with an electromagnetic brake.)

Note:

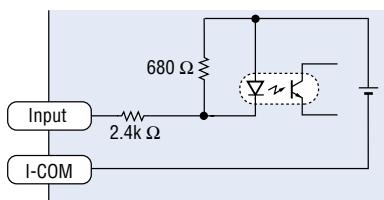
While the motor is running, the temperature of the motor case should not exceed 194°F (90°C).

Introduction	BX	FBL II	AXU	AXH	BHF	ES	US	AC Motor Systems	Brushless DC Motor Systems	DC Input	AC Input
Before Using a Speed Control System											

● Input Signal Circuit

◆ Input Circuit

Common to CW, CCW and SLOW DOWN, FREE*, RST inputs.



* The FREE input is used only with a speed control system with electromagnetic brake.

◆ Connection Example for Input Signals

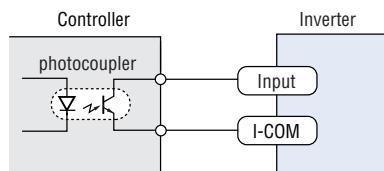
• Controlled by Small Capacity Relays

Inverter		
I-COM	OFF: Stop ON: CW Rotation	
CW	ON: Stop OFF: CCW Rotation	
CCW	OFF: Stop ON: CCW Rotation	
MO	OFF: Built-in speed potentiometer ON: External speed potentiometer	
SD	OFF: Brake ON: Slow down	
FREE*	OFF: Lock ON: Release	
RST	ON: Reset	

• Use a small capacity contact point type relay capable of switching 24 VDC, 5 mA.

* The FREE input is used only with a speed control system with electromagnetic brake.

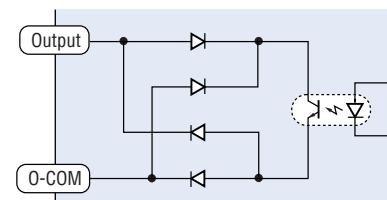
• Electronic Input Control



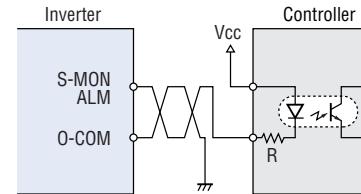
● Output Signal Circuit

◆ Output Circuit

Common to S-MON, ALM outputs.



◆ Connection Example for Output Signals



• An external power source is required since the circuit has an open-collector output configuration as shown in the figure above. There is no need to connect an external power source if no signal outputs are used. Use an external power source of 26.4 VDC or below. Connect a limit resistance according to the power-supply voltage so that the current level doesn't exceed 10 mA.

Speed monitor output: Pulse signals are output at a rate of 12 pulses per revolution of the motor output shaft are output.

(Note that this is monitoring of the speed command issued from the inverter to the motor, not that of the speed measured at the motor's output shaft.)

$$\text{Motor speed: } \frac{\text{S-MON output frequency [Hz]}}{12} \times 60 \text{ [r/min]}$$

Alarm output: This signal is output when a protection function for overload, circuit overheat, overvoltage, undervoltage, overcurrent or EEPROM error has been activated. When an alarm signal is output, this output is turned to OFF ("H" level) between the ALARM OUT and GND terminals.

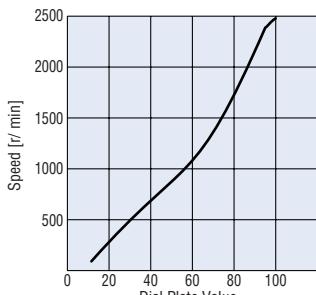
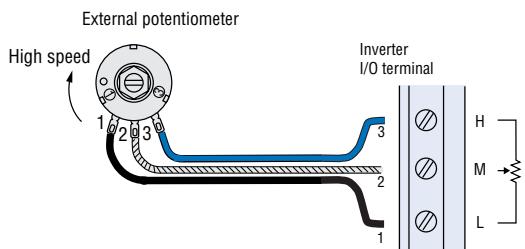
Method of Speed Setting

Speed Control by Built-in Potentiometer

The Built-in speed potentiometer is selected when the MO (speed-setting mode selection input) is set to OFF ("H" level). Turning the Built-in speed potentiometer clockwise sets a faster speed, while turning it counterclockwise brings the motor to a stop.

Speed Control by External Potentiometer

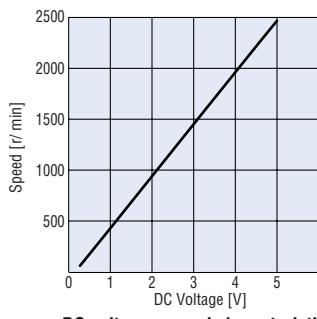
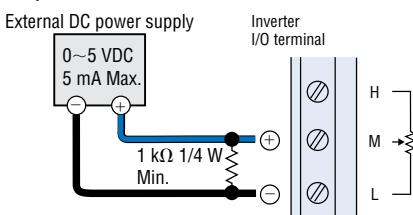
The external speed potentiometer can be used when the MO (speed-setting mode selection input) is set to ON ("L" level). When the optional external speed potentiometer is used, connect it as illustrated below. Turning the external speed potentiometer clockwise sets a faster speed.



External speed potentiometer scale - speed characteristics
(Representative Values)

Speed Control by External DC Voltage

External DC voltage can be used when the MO (speed-setting mode selection input) is set to ON ("L" level). To set the motor speed via external DC voltage, connect a DC power supply as illustrated below. Raising the DC voltage sets a faster speed.



DC voltage - speed characteristics
(Representative Values)

List of Motor and Inverter Combinations

Model name for motor/control unit combinations are shown below

Combination Type Speed Control System

Model	Motor	Gearhead	Inverter
BHF62AT-□RH	BHM62T-G2	BH6G2-□RH	FSP200-1
BHF62AT-□RA		BH6G2-□RA	
BHF62AT-□		BH6G2-□	
BHF62CT-□RH		BH6G2-□RH	
BHF62CT-□RA		BH6G2-□RA	
BHF62CT-□		BH6G2-□	
BHF62ST-□RH		BH6G2-□RH	
BHF62ST-□RA		BH6G2-□RA	
BHF62ST-□		BH6G2-□	

● Enter the gear ratio in the box (□) within the model name.

Round Shaft Speed Control System

Model	Motor	Inverter
BHF62AT-A	BHM62T-A	FSP200-1
BHF62CT-A		FSP200-2
BHF62ST-A		FSP200-3

Combination Type Speed Control System with Electromagnetic Brake

Model	Motor	Gearhead	Inverter
BHF62AMT-□RH	BHM62MT-G2	BH6G2-□RH	FSP200-1
BHF62AMT-□RA		BH6G2-□RA	
BHF62AMT-□		BH6G2-□	
BHF62CMT-□RH		BH6G2-□RH	
BHF62CMT-□RA		BH6G2-□RA	
BHF62CMT-□		BH6G2-□	
BHF62SMT-□RH		BH6G2-□RH	
BHF62SMT-□RA		BH6G2-□RA	
BHF62SMT-□		BH6G2-□	

● Enter the gear ratio in the box (□) within the model name.

Round Shaft Speed Control System with Electromagnetic Brake

Model	Motor	Inverter
BHF62AMT-A	BHM62MT-A	FSP200-1
BHF62CMT-A		FSP200-2
BHF62SMT-A		FSP200-3

AC Motor Speed Controller ES01/ES02

ES01 and **ES02** are Oriental Motor's newest speed controllers designed for ease of its functions and operations. A wide range of speed control motors is available for use with these new controllers.



■ Features

● Multi-Functions

- Speed Control Range
90~1400 r/min (50 Hz) 90~1600 r/min (60 Hz)
- Speed Control Function
Acceleration/deceleration function that enables smooth start and stop

● Speed Control Function

The **ES01/ES02** enables users to regulate the output speed of motors ranging from 6W to 90W.

● IP20-Compliant

The IP20-compliant construction prevents the operator from touching the terminal block, thereby ensuring a high degree of safety.

■ Speed Controller Product Line

● Speed Controller

Model	Voltage
ES01	Single-Phase 100-115 VAC
ES02	Single-Phase 200-230 VAC

● Compatible with Voltages in All Major Countries

The design conforms to typical global safety standards. The CE Marking is used in accordance with the EMC directives and low voltage directives.

● Easy Wiring



Terminals for control-signal lines



Terminals for power-supply cables

For easy wiring the new design provides separate connector terminals for power-supply cables and control-signal lines.

■ Safety Standards and CE Marking

● Speed Controllers

Standards	Certification Body	Standards File No.	CE Marking
UL508			
CSA C.22.2 No.14	UL	E91291	
EN50178			Low Voltage Directive
EN60950			EMC Directive
EN50081-2		Conform to EN Standards	EMC Directive
EN61000-6-2			

● Details of Safety Standards → Page G-2

● The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked incorporated in the equipment.



■ Specifications of Speed Controller

Model Name	ES01	ES02
Voltage	Single-Phase 100-115 VAC ±10%	Single-Phase 200-230 VAC ±10%
Frequency		50/60 Hz
Operable Motor Output Power		World K Series: 6 W, 15 W, 25 W, 40 W, 60 W V Series: 6 W, 15 W, 25 W, 40 W, 60 W, 90 W
Speed Range		50 Hz: 90~1400 r/min, 60 Hz: 90~1600 r/min
Function		Speed Control, Instantaneous Stop, Acceleration/Deceleration
Insulation Resistance	100 MΩ or more when 500 VDC is applied between the PE terminal and the power supply terminals, all the pins and the frame.	
Dielectric Strength	Sufficient to withstand 3.0 kV at 50 Hz, 60 Hz applied between all the pins and the frame for 1 minute. Sufficient to withstand 1.5 kV at 50 Hz, 60 Hz applied between the PE terminals and the power supply terminals for 1 min.	
Ambient Temperature Range		32°F~104°F (0°C~+40°C) (nonfreezing)
Ambient Humidity		85% maximum (noncondensing)
Degree of Protection		IP 20 (with cover)

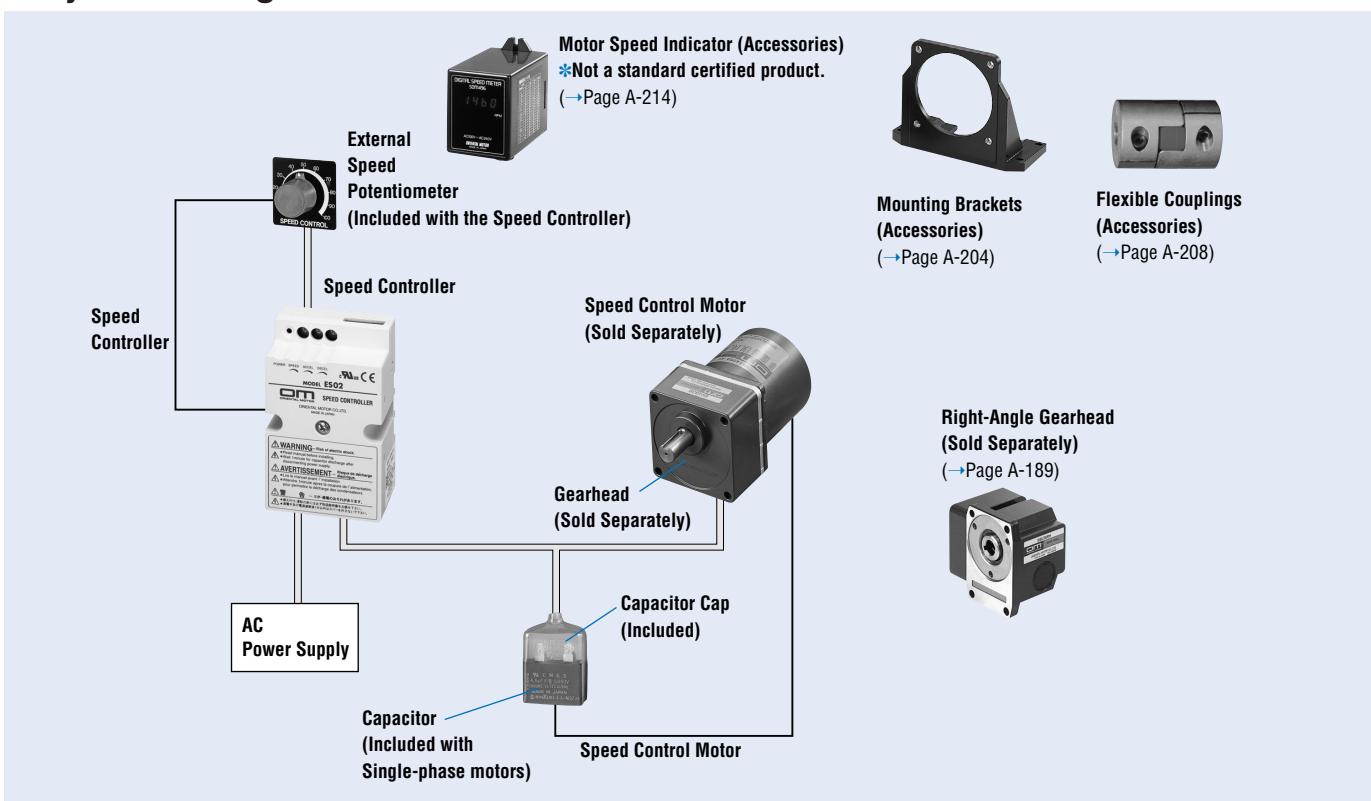
Notes:

- These models cannot be used for applications requiring the control of more than one motor/controller set by the same external potentiometer.
- When the motor is commanded to stop immediately, the large braking current will flow to the motor. See page B-115 for the braking current.

■ Dimensions → Page B-103

■ Connection and Operation → Page B-111

■ System Configuration



The system configuration shown is an example. Other configurations are available.

■ Applicable Speed Control Motor (Sold Separately)

● World K Series Speed Control Motors 6 W~60 W

A tachometer generator built into our standard AC induction and reversible motors allows a wide range of speed control. This simple structure delivers high reliability at a low cost, making this system a popular solution for a wide range of applications.

● V Series Speed Control Motors 6 W~90 W

The V series speed control motors provide quiet operation, long life and high strength performance, making them the perfect solution for many applications. The motor and gearbox come pre-assembled to make installation easy.

■ Safety Standards and CE Marking

● Speed Control Motors

Standards	Certification Body	Standards File No.	CE Marking
UL1004			
UL2111			
CSA C.22.2 No.100	UL	E64199 (6 W) E64197 (15 W~90 W)	
CSA C.22.2 No.77			Low Voltage Directive
EN60950			
EN60034-1			
EN60034-5		Conform to EN Standards	
IEC60034-11*			

* 15 W~40 W Type

● Details of Safety Standards → Page G-2

● When the motor is approved under various standards, the model name on the nameplate is the approved model name.

List of Safety Standard Approved Products → Page G-17, G-18

■ Product Number Code
● V Series Speed Control Motors

V S I 4 25 A - 30 U

①	V Series
②	Speed Control Motor
③	I: Induction Motor R: Reversible Motor
④	Motor Frame Size
⑤	Output Power (W) Example 25 : 25 W
⑥	Voltage A: Single-Phase 100/110/115 VAC C: Single-Phase 200/220/230 VAC
⑦	Gear Ratio Example 30 : Gear ratio of 30:1
⑧	With Capacitor for U: Single-Phase 110-115 VAC E: Single-Phase 220-230 VAC

■ Product Line

● V Series Speed Control Motors (Combination Type)

◆ Single-Phase 110/115 VAC

Output Power HP	Induction Motors	Reversible Motors	Speed Controller
1/125	VSI206A-□U	VSR206A-□U	ES01
1/50	VSI315A-□U	VSR315A-□U	
1/30	VSI425A-□U	VSR425A-□U	
1/19	VSI540A-□U	VSR540A-□U	
1/12	VSI560A-□U	VSR560A-□U	
1/8	VSI590A-□U	VSR590A-□U	

- Enter the gear ratio in the box (□) within the model name.

◆ Single-Phase 220/230 VAC

Output Power HP	Induction Motors	Reversible Motors	Speed Controller
1/125	VSI206C-□E	VSR206C-□E	ES02
1/50	VSI315C-□E	VSR315C-□E	
1/30	VSI425C-□E	VSR425C-□E	
1/19	VSI540C-□E	VSR540C-□E	
1/12	VSI560C-□E	VSR560C-□E	
1/8	VSI590C-□E	VSR590C-□E	

- Enter the gear ratio in the box (□) within the model name.

■ Specifications of Applicable Motors

● World K Series Induction Motors – Continuous Rating

◆ Single-Phase 110/115 VAC Applicable Speed Controller: ESO1



Model		Maximum Output Power	Voltage	Frequency	Speed Range*		Permissible Torque			Starting Torque	Current	Power Consumption	Capacitor		
Pinion Shaft Type	Round Shaft Type	HP	W	VAC	Hz	r/min	1200 r/min oz-in	90 r/min mN-m	oz-in	mN-m	A	W	μF		
(ZP) 2IK6RGN-AWU	2IK6RA-AWU	1/125	6	Single-Phase 110 Single-Phase 115	60	90~1600	7.1	50	4.9	35	5.6	40	0.28	29	2.5
(TP) 3IK15RGN-AWU	3IK15RA-AWU	1/50	15	Single-Phase 110 Single-Phase 115	60	90~1600	17.7	125	5.9	42	9.2	65	0.48	46	4.5
(TP) 4IK25RGN-AWU	4IK25RA-AWU	1/30	25	Single-Phase 110 Single-Phase 115	60	90~1600	26	185	7.1	50	17.0	120	0.75	58 69	6.5
(TP) 5IK40RGN-AWU	5IK40RA-AWU	1/19	40	Single-Phase 110 Single-Phase 115	60	90~1600	31	225	9.5	67	25 28	180 200	1.1	107	9
(TP) 5IK60RGU-AWU	5IK60RA-AWU	1/12	60	Single-Phase 110 Single-Phase 115	60	90~1600	69	490	29	210	45	320	2	180	18

(ZP): These motors are impedance protected.

(TP): These motors contain a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

* The speed range is under no load conditions.



◆ Single-Phase 220/230 VAC Applicable Speed Controller: ESO2

Model		Maximum Output Power	Voltage	Frequency	Speed Range*		Permissible Torque			Starting Torque	Current	Power Consumption	Capacitor		
Pinion Shaft Type	Round Shaft Type	HP	W	VAC	Hz	r/min	1200 r/min oz-in	90 r/min mN-m	oz-in	mN-m	A	W	μF		
(ZP) 2IK6RGN-CWE	2IK6RA-CWE	1/125	6	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	5.9 7.1	42 50	4.5	32	4.9 5.6	35 40	0.14	28 29	0.6
(TP) 3IK15RGN-CWE	3IK15RA-CWE	1/50	15	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	15.6 17.7	110 125	5.3	38	9.2 10.6	65 75	0.23	43 46 44 47	1
(TP) 4IK25RGN-CWE	4IK25RA-CWE	1/30	25	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	26 28	190 200	7.1	50	15.6 17.0	110 120	0.34	63 67 63 69	1.5
(TP) 5IK40RGN-CWE	5IK40RA-CWE	1/19	40	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	42 39	300 280	10.6	75	26 28	190 200	0.55	96 104 99 105	2.3
(TP) 5IK60RGU-CWE	5IK60RA-CWE	1/12	60	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	65 69	460 490	28	200	45	320	0.84 0.89 0.85	155 175 158	4
													0.89	172	

(ZP): These motors are impedance protected.

(TP): These motors contain a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

* The speed range is under no load conditions.

● World K Series Reversible Motors – 30-Minute Rating
 ◆ Single-Phase 110/115 VAC Applicable Speed Controller: ESO1

Model		Maximum Output Power	Voltage	Frequency	Speed Range*		Permissible Torque		Starting Torque	Current	Power Consumption	Capacitor			
Pinion Shaft Type	Round Shaft Type	HP	W	VAC	Hz	r/min	oz-in	mN·m	oz-in	mN·m	A	W	μF		
(ZP) 2RK6RGN-AWU	2RK6RA-AWU	1/125	6	Single-Phase 110 Single-Phase 115	60	90~1600	7.1	50	7.1	50	6.3	45	0.32	32	3.5
(TP) 3RK15RGN-AWU	3RK15RA-AWU	1/50	15	Single-Phase 110 Single-Phase 115	60	90~1600	17.7	125	12	85	14.2	100	0.6	59	6
(TP) 4RK25RGN-AWU	4RK25RA-AWU	1/30	25	Single-Phase 110 Single-Phase 115	60	90~1600	29	205	15.6	110	19.8	140	0.95	90	8
(TP) 5RK40RGN-AWU	5RK40RA-AWU	1/19	40	Single-Phase 110 Single-Phase 115	60	90~1600	45	320	22	155	34 36	240 260	1.4	138	12
(TP) 5RK60RGU-AWU	5RK60RA-AWU	1/12	60	Single-Phase 110 Single-Phase 115	60	90~1600	69	490	38	270	53	380	2.2	201	20

(ZP): These motors are impedance protected.

(TP): These motors contain a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

- The permissible torque and the starting torque of reversible motors are shown in terms without the brake applied. Please keep in mind that you should select a suitable motor with enough torque, when designing the equipment.

*The speed range is under no load conditions.

◆ Single-Phase 220/230 VAC Applicable Speed Controller: ESO2

Model		Maximum Output Power	Voltage	Frequency	Speed Range*		Permissible Torque		Starting Torque	Current	Power Consumption	Capacitor			
Pinion Shaft Type	Round Shaft Type	HP	W	VAC	Hz	r/min	oz-in	mN·m	oz-in	mN·m	A	W	μF		
(ZP) 2RK6RGN-CWE	2RK6RA-CWE	1/125	6	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	6.3 7.1	45 50	7.1 7.1	50 50	0.15 0.16	33	0.8		
(TP) 3RK15RGN-CWE	3RK15RA-CWE	1/50	15	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	17.7 17.7	125 125	12.3 87	14.2 14.2	100 100	0.29	59	1.5	
(TP) 4RK25RGN-CWE	4RK25RA-CWE	1/30	25	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	29 29	205 205	16.3 115	19.8 22	140 155	0.44	88	2	
(TP) 5RK40RGN-CWE	5RK40RA-CWE	1/19	40	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	45 45	320 320	24 24	170 170	36 38	260 270	0.72	133	3.5
(TP) 5RK60RGU-CWE	5RK60RA-CWE	1/12	60	Single-Phase 220 Single-Phase 230	50 60	90~1400 90~1600	69 69	490 490	39 39	280 280	59 53	420 380	1.0 1.0	185 198	5
											65	460	1.0	188	
											53	380	1.1	202	

(ZP): These motors are impedance protected.

(TP): These motors contain a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops. When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

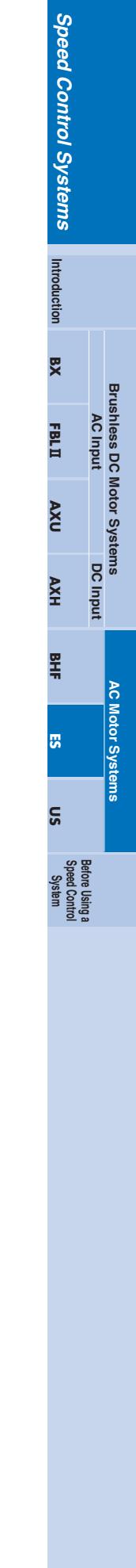
- The permissible torque and the starting torque of reversible motors are shown in terms without the brake applied. Please keep in mind that you should select a suitable motor with enough torque, when designing the equipment.

*The speed range is under no load conditions.

● **V Series Induction Motors – Continuous Rating**

◆ Single-Phase 115 VAC Applicable Speed Controller: **ES01** Unit=Upper Values: lb-in/Lower Values: N·m

Model Combination Type	Gear Ratio Speed	5 6 9 15 18 30 36 60 90 120 180 300 360												
		5	6	9	15	18	30	36	60	90	120	180	300	360
VSI206A-□U	1200 r/min	2.0 0.23	2.3 0.27	3.6 0.41	6.0 0.68	7.1 0.81	11.5 1.3	13.2 1.5	23 2.6	34 3.9	46 5.2	53 6	53 6	53 6
	90 r/min	1.41 0.16	1.68 0.19	2.4 0.28	4.1 0.47	5.0 0.57	7.9 0.9	9.7 1.1	15.9 1.8	23 2.7	31 3.6	45 5.1	53 6	53 6
VSI315A-□U	1200 r/min	4.9 0.56	6.0 0.68	8.8 1.0	15.0 1.7	17.7 2.0	28 3.2	34 3.9	57 6.5	85 9.7	88 10	88 10	88 10	88 10
	90 r/min	1.68 0.19	2.0 0.23	3.0 0.34	5.0 0.57	6.0 0.68	9.7 1.1	11.5 1.3	19.4 2.2	29 3.3	38 4.3	53 6.1	88 10	88 10
VSI425A-□U	1200 r/min	7.3 0.83	8.8 1.0	13.2 1.5	22 2.5	26 3.0	42 4.8	50 5.7	84 9.5	126 14.3	141 16	141 16	141 16	141 16
	90 r/min	2.0 0.23	2.3 0.27	3.6 0.41	6.0 0.68	7.1 0.81	11.5 1.3	13.2 1.5	23 2.6	34 3.9	46 5.2	64 7.3	107 12.2	129 14.6
VSI540A-□U	1200 r/min	8.8 1.0	10.6 1.2	15.9 1.8	26 3.0	31 3.6	51 5.8	61 7.0	102 11.6	153 17.4	193 21.9	260 30	260 30	—
	90 r/min	2.6 0.3	3.1 0.36	4.7 0.54	7.9 0.9	9.7 1.1	15.0 1.7	18.5 2.1	30 3.5	46 5.2	57 6.5	86 9.8	144 16.3	—
VSI560A-□U	1200 r/min	19.4 2.2	23 2.6	35 4.0	58 6.6	69 7.9	111 12.6	134 15.2	220 25.3	260 30	260 30	260 30	260 30	—
	90 r/min	8.4 0.95	9.7 1.1	15.0 1.7	24 2.8	30 3.4	47 5.4	57 6.5	95 10.8	144 16.3	180 20.4	260 30	260 30	—
VSI590A-□U	1200 r/min	29 3.3	34 3.9	52 5.9	87 9.9	100 11.3	166 18.8	200 22.6	330 37.7	350 40	350 40	—	—	—
	90 r/min	8.4 0.95	9.7 1.1	15.0 1.7	24 2.8	29 3.3	47 5.4	57 6.5	95 10.8	135 15.3	180 20.4	270 30.6	—	—



■ Gearmotor — Torque Table when a Right-Angle Gearhead is Attached

Right-Angle Gearhead is available for World K Series.

→Page A-196

■ Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) →Page A-11

Gearhead →Page A-11

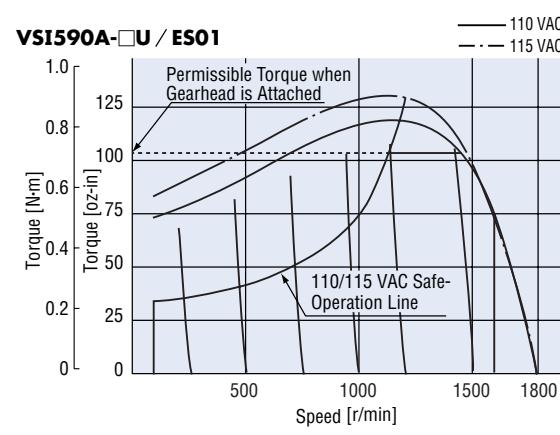
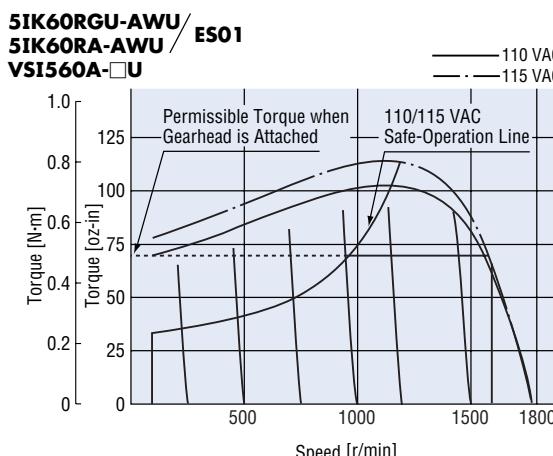
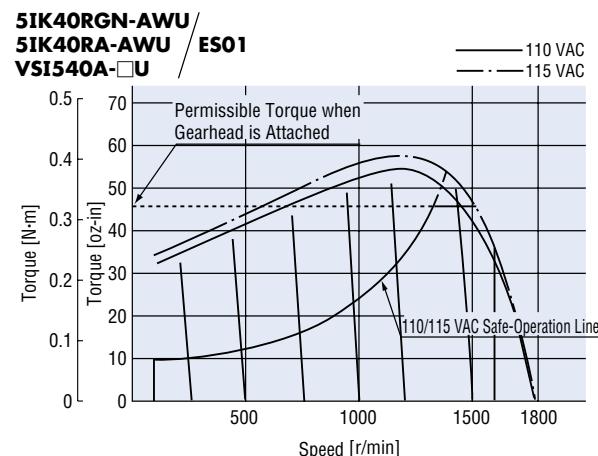
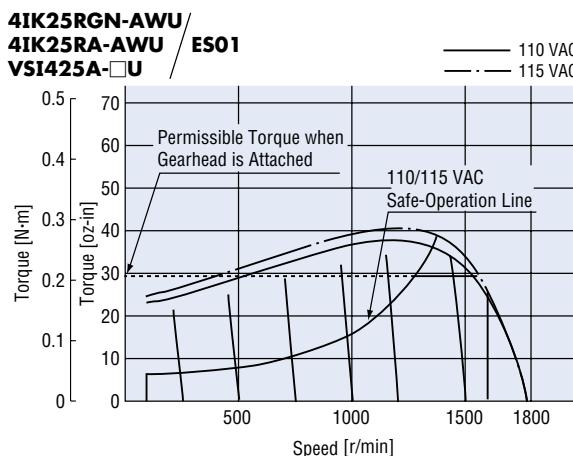
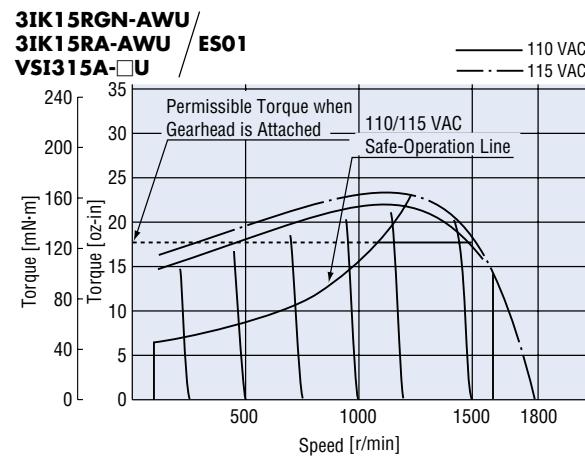
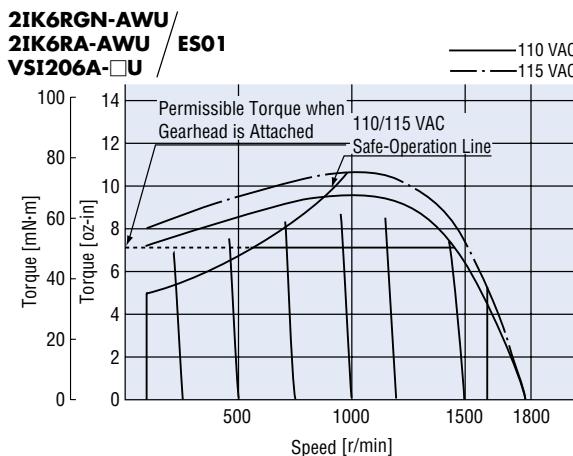
■ Permissible Load Inertia J for Gearhead

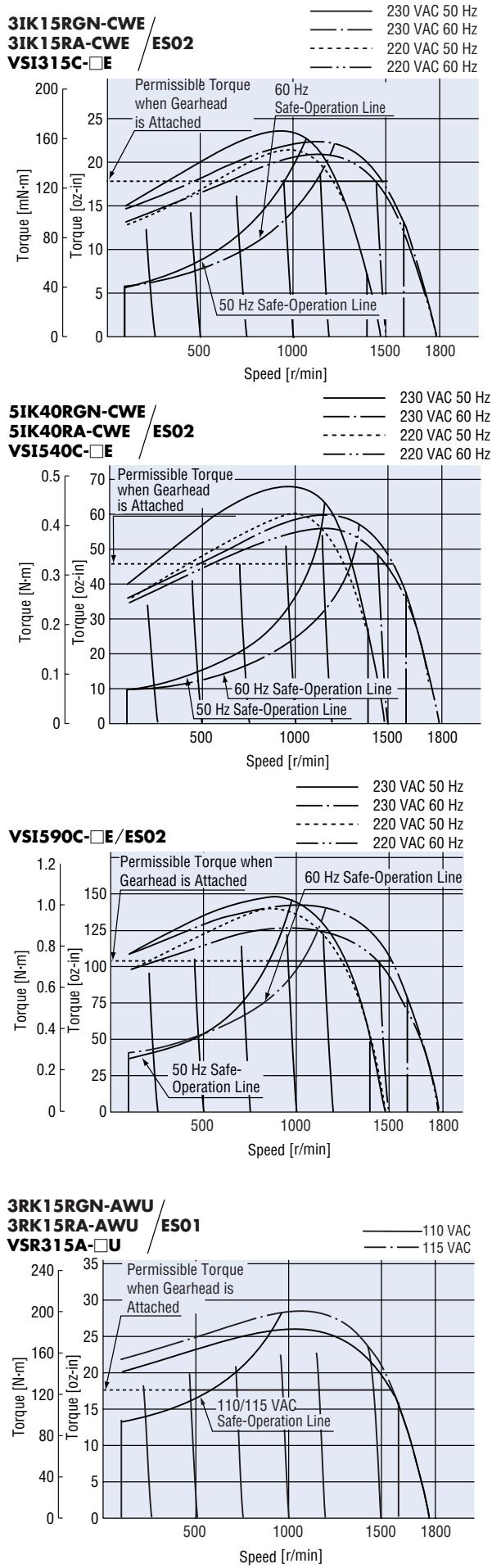
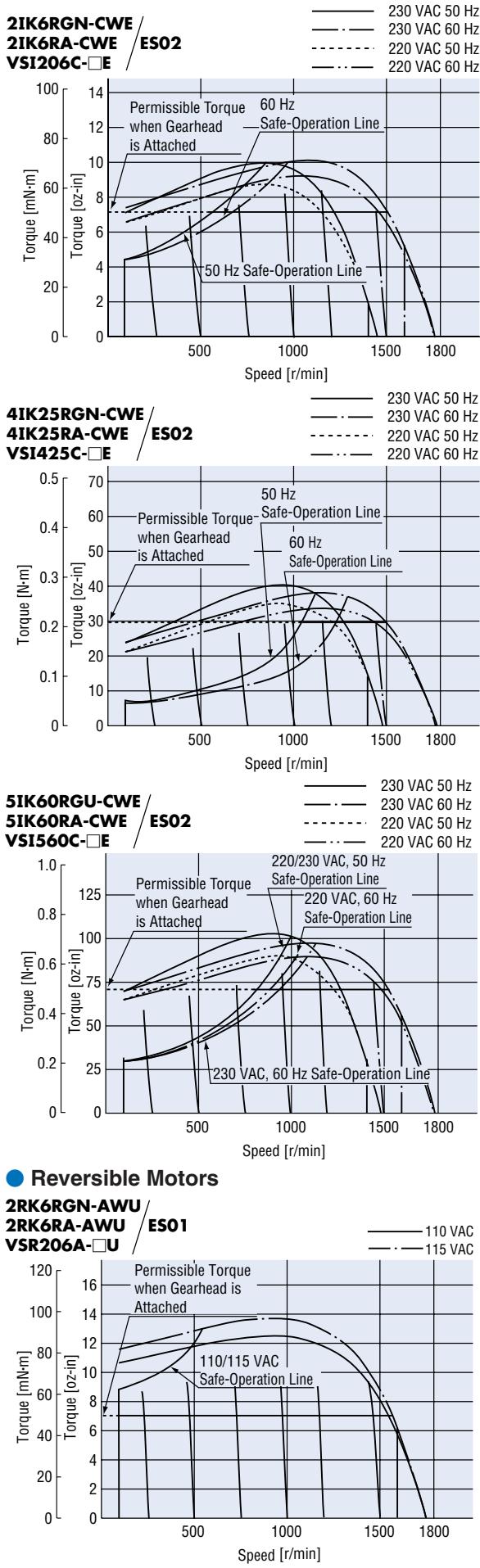
→Page A-12

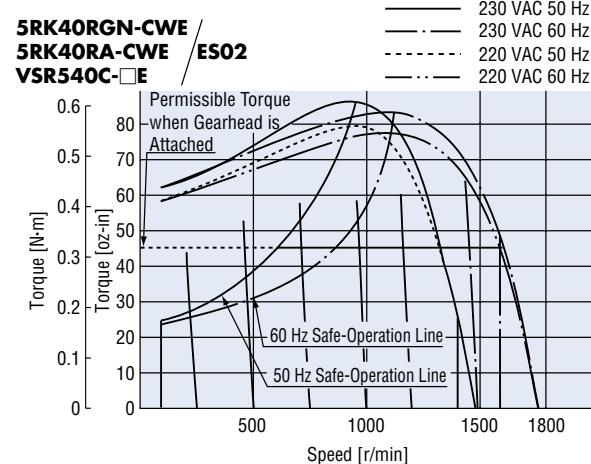
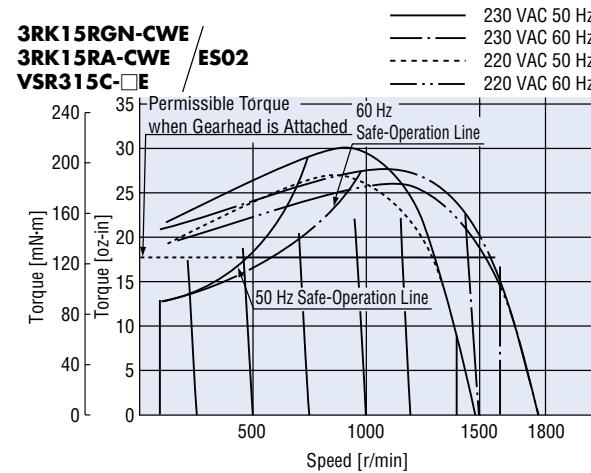
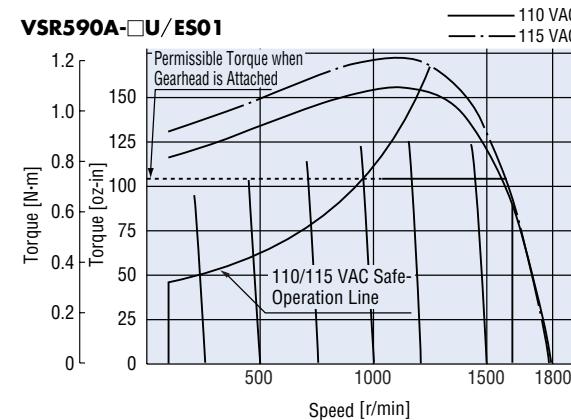
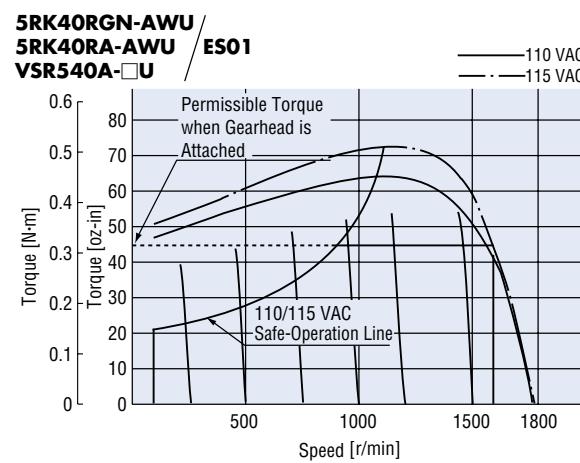
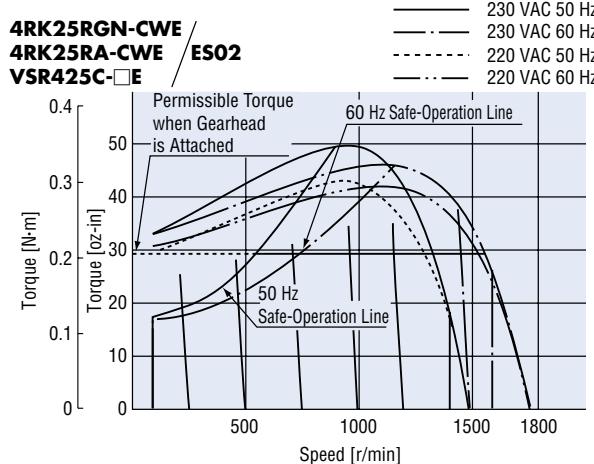
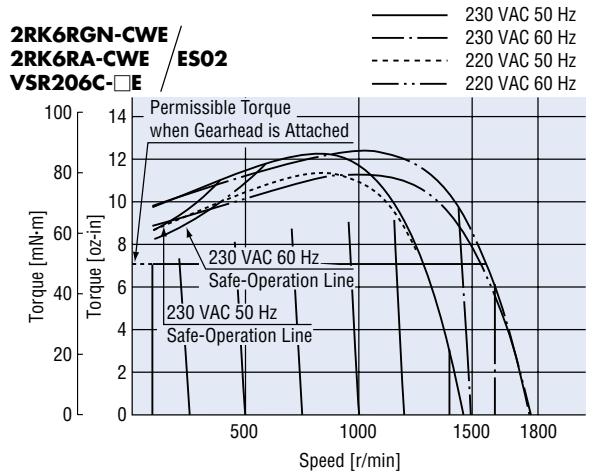
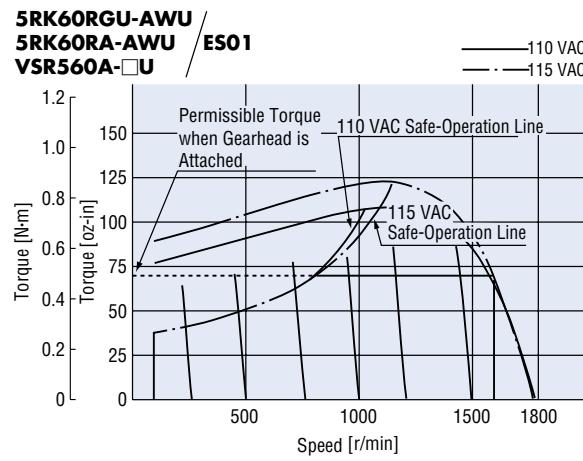
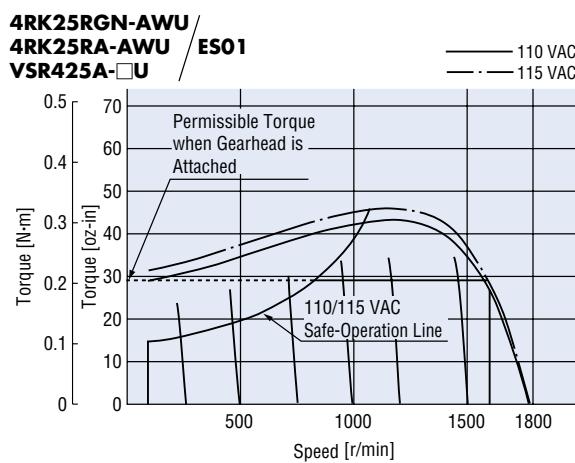
■ Speed — Torque Characteristics

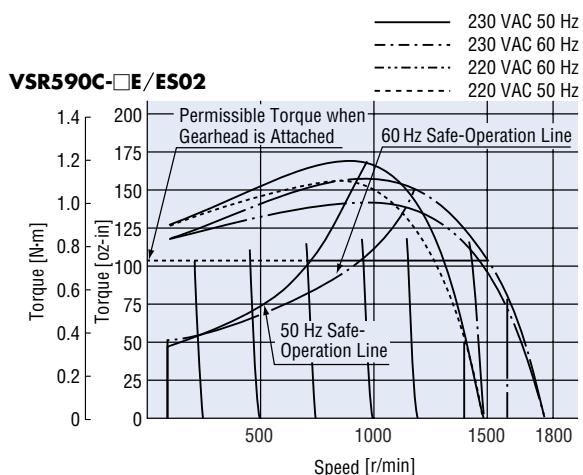
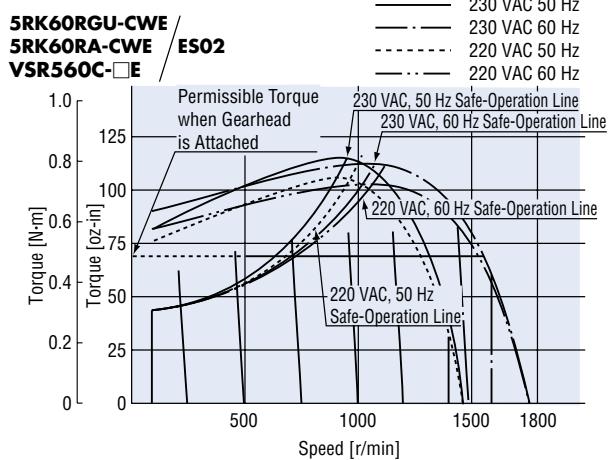
● Induction Motors

Enter the gear ratio in the box (□) with in the V Series combination type model name. The characteristics of V Series are for motor's only.







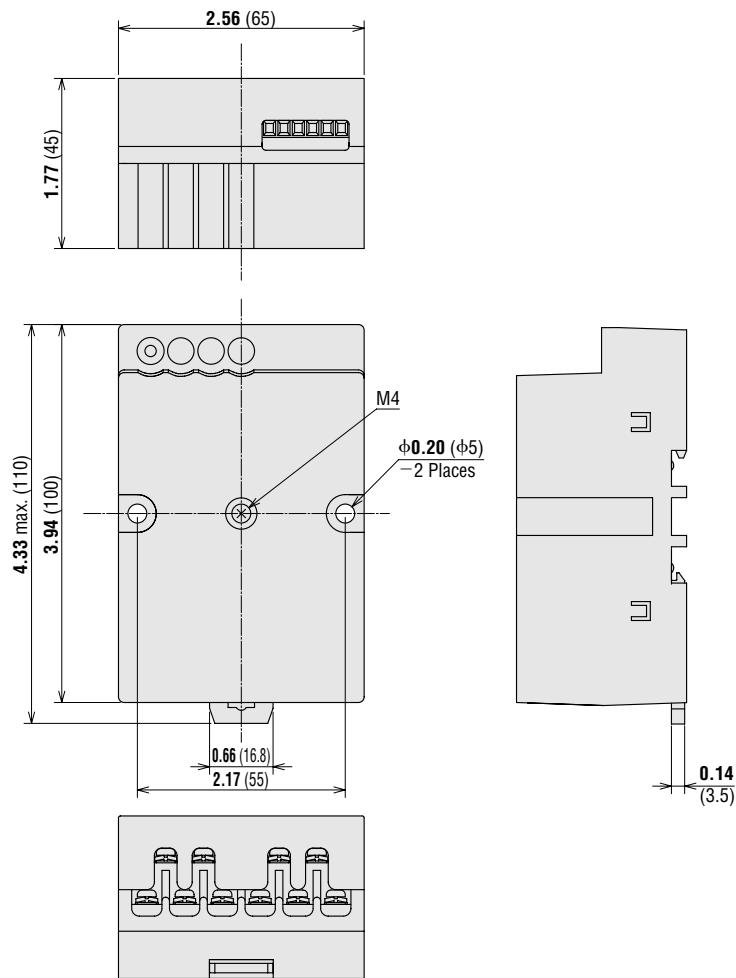


Dimensions

Scale 1/4, Unit = inch (mm)

Speed Controller: **ESO1, ESO2** (Scale 1/2)
Weight: 0.4 lb. (0.18 kg)

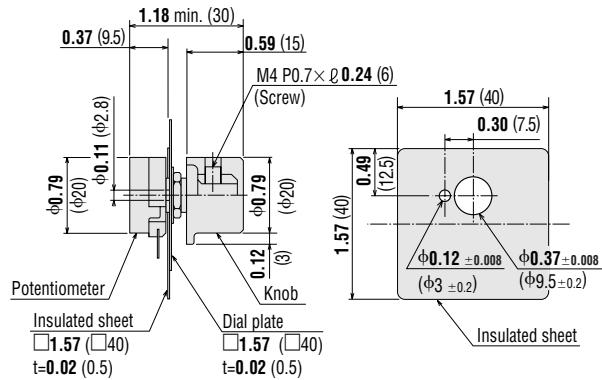
DXF A394



External Speed Potentiometer (Included)

(Scale 1/2)

PAVR-20KZ



◆ Motor/Gearhead (Pinion Shaft Type)

4IK25RGN-AWU

4IK25RGN-CWE

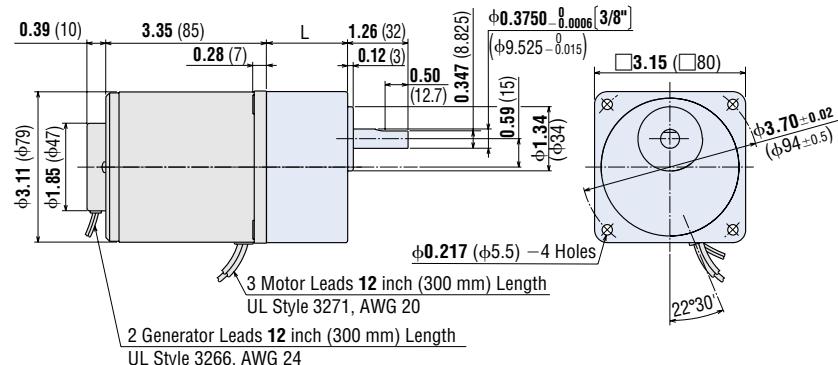
4RK25RGN-AWU

4RK25RGN-CWE

Weight: 3.5 lb. (1.6 kg)

4GN□KA

Weight: 1.43 lb. (0.65 kg)

DXF A067AU (4GN3KA~18KA)
A067BU (4GN25KA~180KA)

4GN3KA-18KA: L = 1.26 (32)

4GN25KA-180KA: L = 1.67 (42.5)

◆ Round Shaft Type

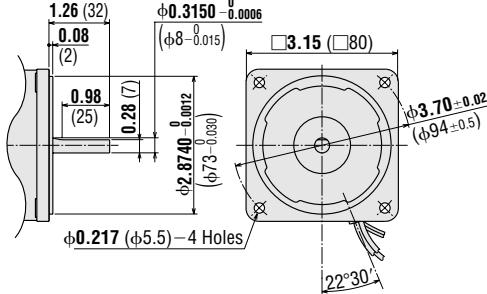
4IK25RA-AWU

4IK25RA-CWE

4RK25RA-AWU

4RK25RA-CWE

Weight: 3.5 lb. (1.6 kg)

DXF A366

◆ Motor/Gearhead (Pinion Shaft Type)

5IK40RGN-AWU

5IK40RGN-CWE

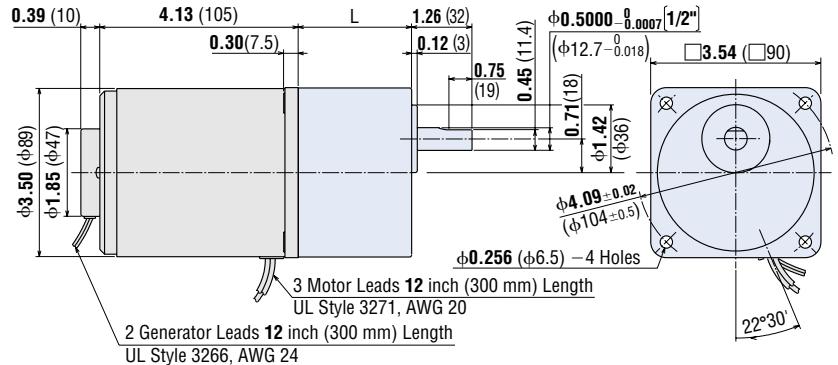
5RK40RGN-AWU

5RK40RGN-CWE

Weight: 5.7 lb. (2.6 kg)

5GN□KA

Weight: 3.3 lb. (1.5 kg)

DXF A068AU (5GN3KA~18KA)
A068BU (5GN25KA~180KA)

5GN3KA-18KA: L = 1.65 (42)

5GN25KA-180KA: L = 2.36 (60)

◆ Round Shaft Type

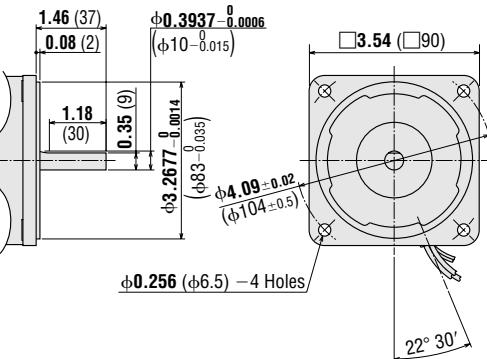
5IK40RA-AWU

5IK40RA-CWE

5RK40RA-AWU

5RK40RA-CWE

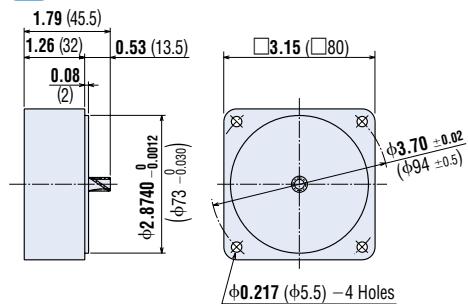
Weight: 5.7 lb. (2.6 kg)

DXF A367

● Decimal Gearhead

Can be connected to 4IK25RGN, 4RK25RGN type

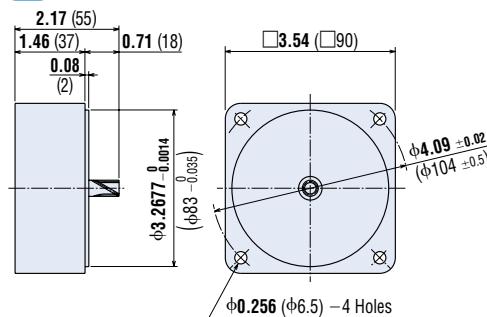
4GN10XK Weight: 0.88 lb. (0.4 kg)

DXF A013

● Decimal Gearhead

Can be connected to 5IK40RGN, 5RK40RGN type

5GN10XK Weight: 1.3 lb. (0.6 kg)

DXF A022

◆ Motor/Gearhead (Pinion Shaft Type)

5IK60RGU-AWU

5IK60RGU-CWE

5RK60RGU-AWU

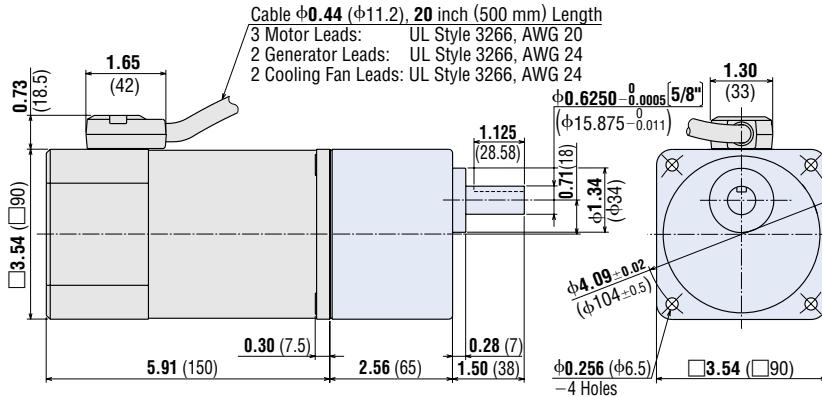
5RK60RGU-CWE

Weight: 7.1 lb. (3.2 kg)

5GU□KA

Weight: 3.3 lb. (1.5 kg)

DXF A069U (5GU3KA~180KA)



◆ Round Shaft Type

5IK60RA-AWU

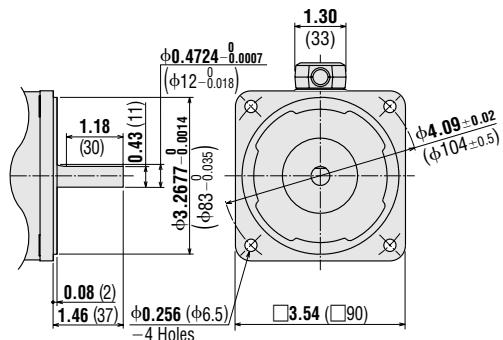
5IK60RA-CWE

5RK60RA-AWU

5RK60RA-CWE

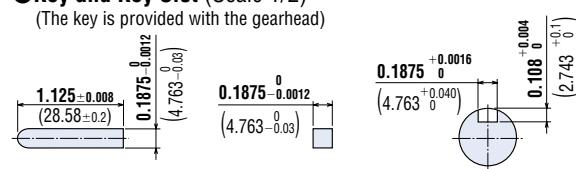
Weight: 7.1 lb. (3.2 kg)

DXF A358



● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)

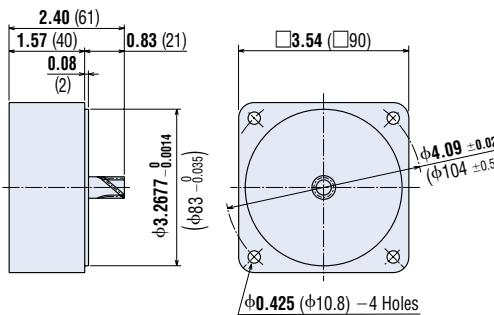


● Decimal Gearhead

Can be connected to 5IK60RGU, 5RK60RGU type

5GU10XKB Weight: 1.3 lb. (0.6 kg)

DXF A029



● V Series

◆ Combination Type

VSI206A[C]-□U[E]

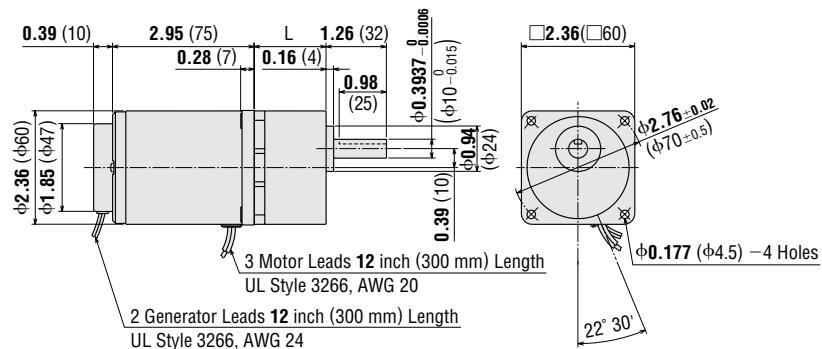
VSR206A[C]-□U[E]

Weight: 2.9 lb. (1.3 kg) (Including Gearhead)

DXF A216A (Gear Ratio: 5~18)

A216B (Gear Ratio: 30~120)

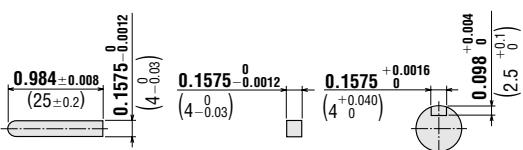
A216C (Gear Ratio: 180~360)



Gear Ratio: 5~18: L = 1.34 (34)
 Gear Ratio: 30~120: L = 1.5 (38)
 Gear Ratio: 180~360: L = 1.69 (43)

● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



◆ Combination Type

VSI315A[C]-□U[E]

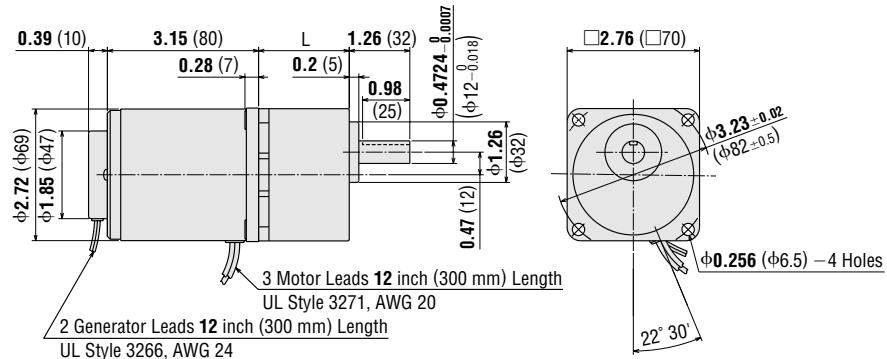
VSR315A[C]-□U[E]

Weight: 4.0 lb. (1.8 kg) (Including Gearhead)

DXF A243A (Gear Ratio: 5~18)

A243B (Gear Ratio: 30~120)

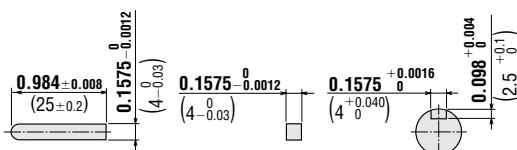
A243C (Gear Ratio: 180~360)



Gear Ratio: 5~18: L = 1.5 (38)
 Gear Ratio: 30~120: L = 1.69 (43)
 Gear Ratio: 180~360: L = 1.89 (48)

● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



◆ Combination Type

VSI425A[C]-□U[E]

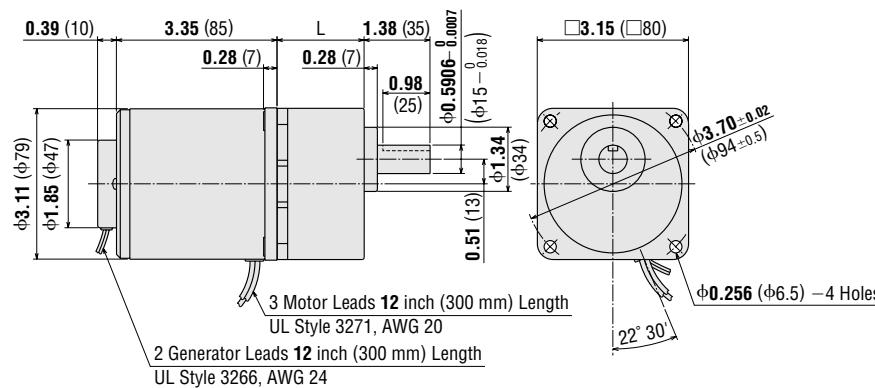
VR425A[C]-□U[E]

Weight: 5.7 lb. (2.6 kg) (Including Gearhead)

DXF A217A (Gear Ratio: **5~18**)

A217B (Gear Ratio: **30~120**)

A217C (Gear Ratio: **180~360**)



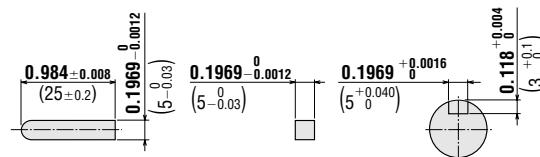
Gear Ratio: 5~18: L = **1.61** (41)

Gear Ratio: 30~120: L = **1.81** (46)

Gear Ratio: 180~360: L = **2.01** (51)

● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



◆ Combination Type

VSI540A[C]-□U[E]

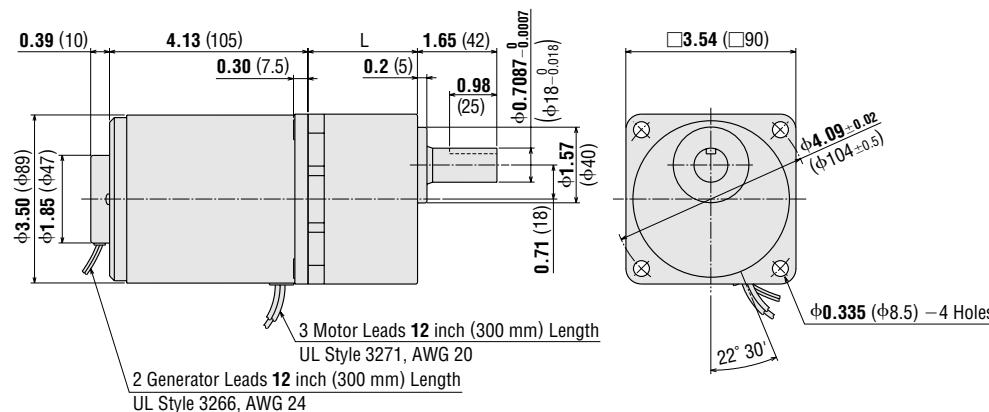
VR540A[C]-□U[E]

Weight: 9.0 lb. (4.1 kg) (Including Gearhead)

DXF A218A (Gear Ratio: **5~18**)

A218B (Gear Ratio: **30~90**)

A218C (Gear Ratio: **120~300**)



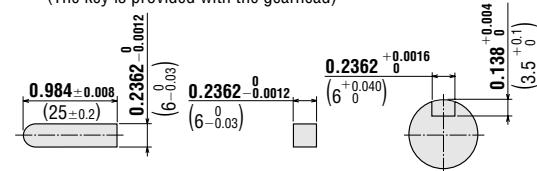
Gear Ratio: 5~18: L = **1.77** (45)

Gear Ratio: 30~90: L = **2.28** (58)

Gear Ratio: 120~300: L = **2.52** (64)

● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



◆ Combination Type

VSI560A[C]-□U[E]

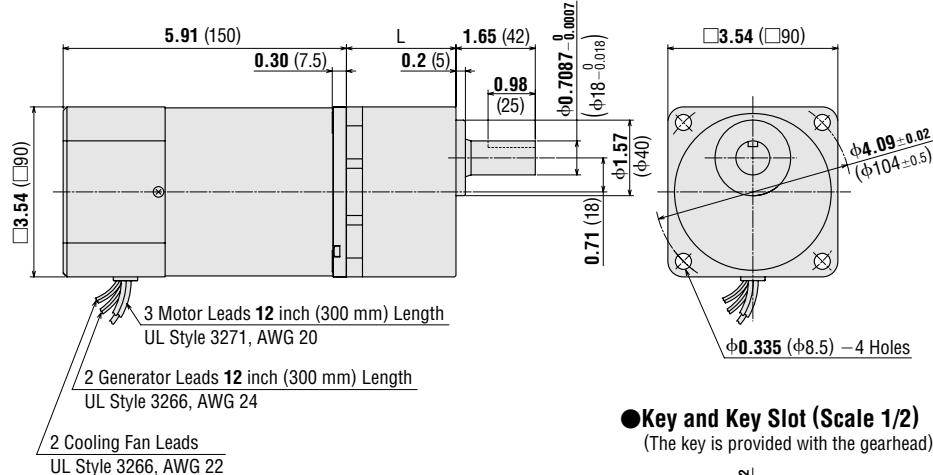
VSR560A[C]-□U[E]

Weight: 10.3 lb. (4.7 kg) (Including Gearhead)

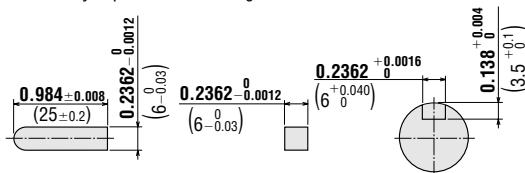
DXF A395A (Gear Ratio: 5~18)

A395B (Gear Ratio: 30~90)

A395C (Gear Ratio: 120~300)



● Key and Key Slot (Scale 1/2)
(The key is provided with the gearhead)



◆ Combination Type

VSI590A[C]-□U[E]

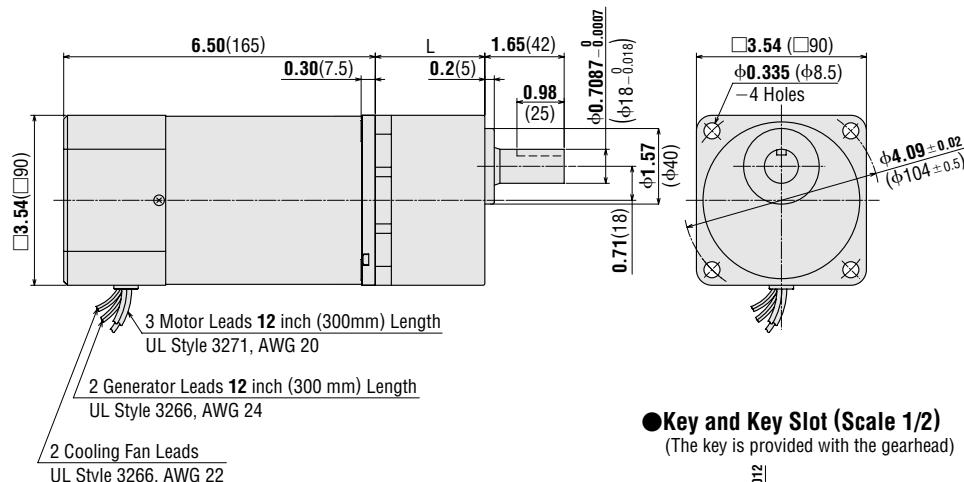
VSR590A[C]-□U[E]

Weight: 11.4 lb. (5.2 kg) (Including Gearhead)

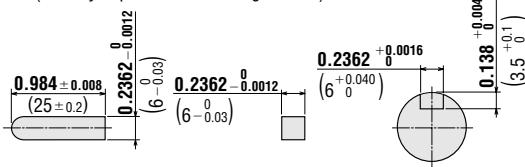
DXF A396A (Gear Ratio: 5~15)

A396B (Gear Ratio: 18~36)

A396C (Gear Ratio: 60~180)



● Key and Key Slot (Scale 1/2)
(The key is provided with the gearhead)

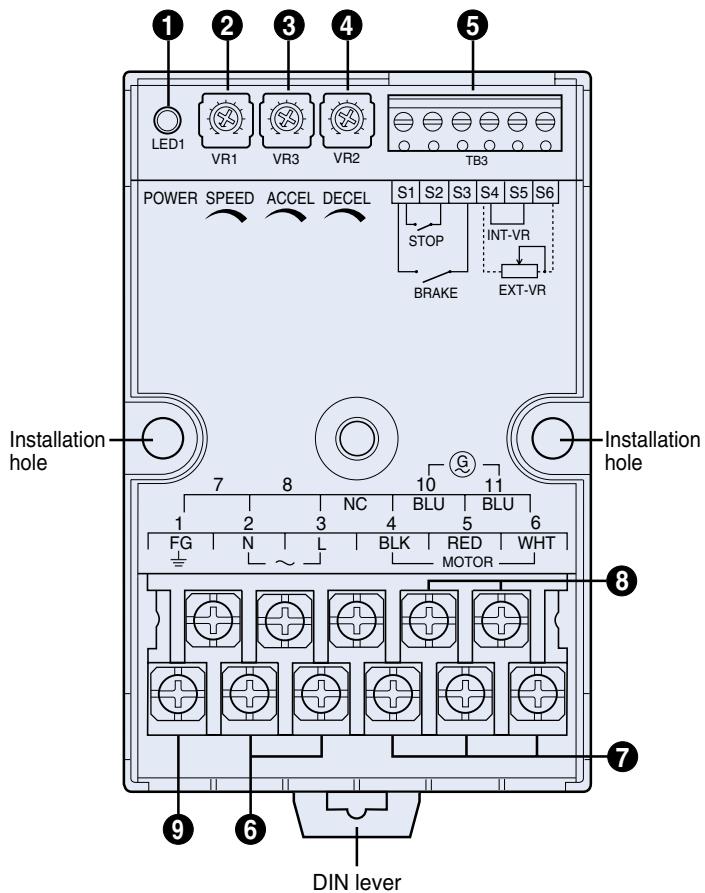


Introduction	BX	FBL II	AXU	DC Input	AC Input	Brushless DC Motor Systems	AC Motor Systems
							Before Using a Speed Control System

■ Connection and Operation

● Names and Function of Parts

The illustration has the cover removed. Install the cover after connection.



① POWER LED

Turns on (green) while power is being supplied.

② Internal speed potentiometer

Set the motor's operating speed.

③ Acceleration time potentiometer

Set the acceleration time for motor startup.

④ Deceleration time potentiometer

Set the deceleration time for motor stop.

⑤ Control input terminal

S1 Common terminal for running and braking

S2 Run/Stop input

Runs (OFF) or stops (ON) the motor.

S3 Run/Brake input

Runs (OFF) or brakes (ON) the motor.

S4, S5, S6 Speed potentiometer inputs

When S4 and S5 are shorted, the speed can be set using the internal speed potentiometer (INT-VR).

When S4 and S5 are open, the speed can be set using an external speed potentiometer (EXT-VR).

When using an external speed potentiometer, connect it to S4 and S6.

⑥ Power connection terminal (terminals 2 and 3)

⑦ Motor connection terminal (terminals 4, 5 and 6)

⑧ Generator connection terminal (terminals 10 and 11)

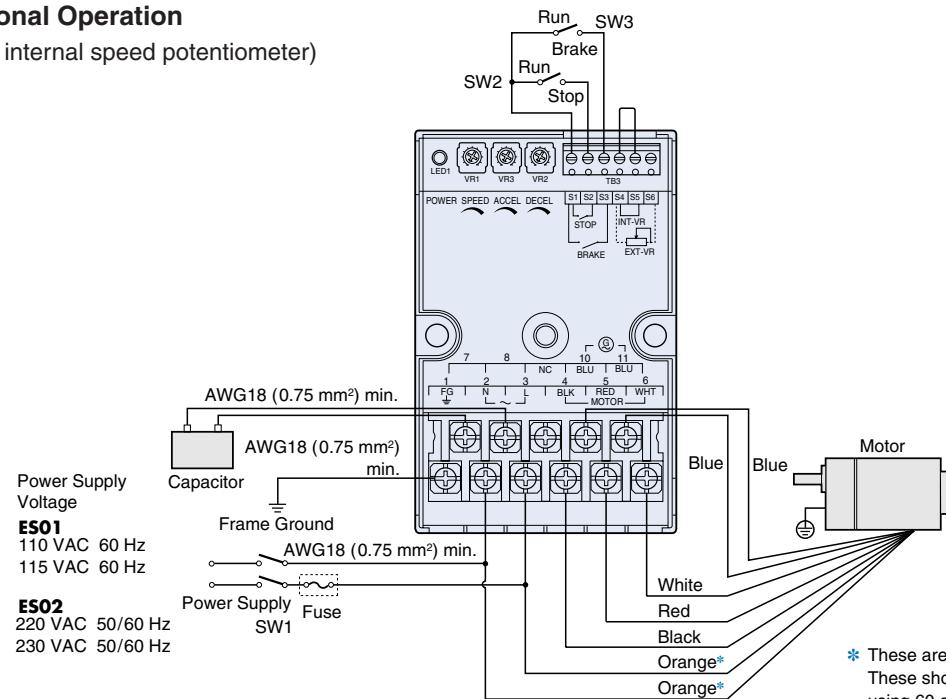
Connect the blue generator lead wires.

⑨ FG terminal (terminal 1)

● Connection Diagrams

◆ Uni-directional Operation

(When using internal speed potentiometer)

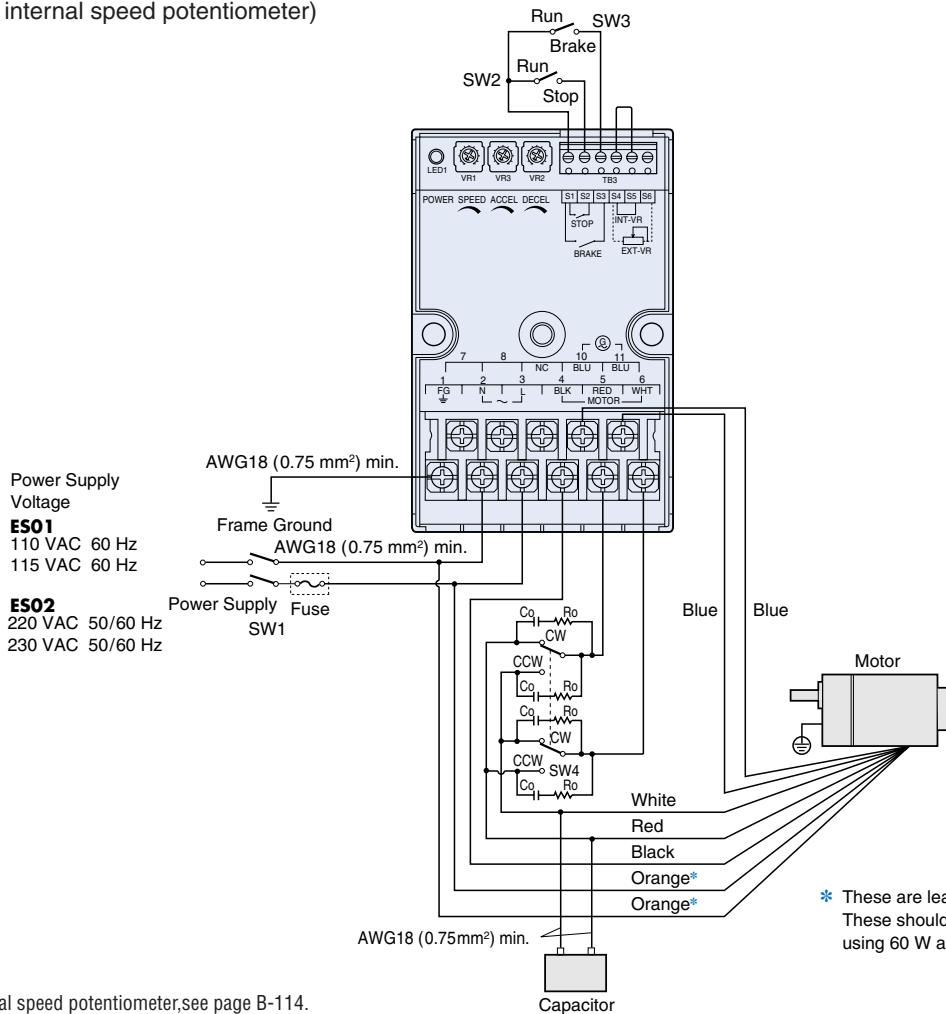


* These are lead wires for the cooling fan.
These should be connected only when using 60 and 90 W type.

- For uni-directional operation, connect the lead wires of the motor to the controller in this order: For CW operation, connect the Red wire to terminal #5 and the White wire to terminal #6. For CCW operation, connect the White wire to terminal #5 and the Red wire to terminal #6.
- When using external speed potentiometer, see page B-114.

◆ Bi-directional Operation

(When using internal speed potentiometer)



* These are lead wires for the cooling fan.
These should be connected only when using 60 W and 90 W type.

- When using external speed potentiometer, see page B-114.

● Specifications of the Switches and Fuse

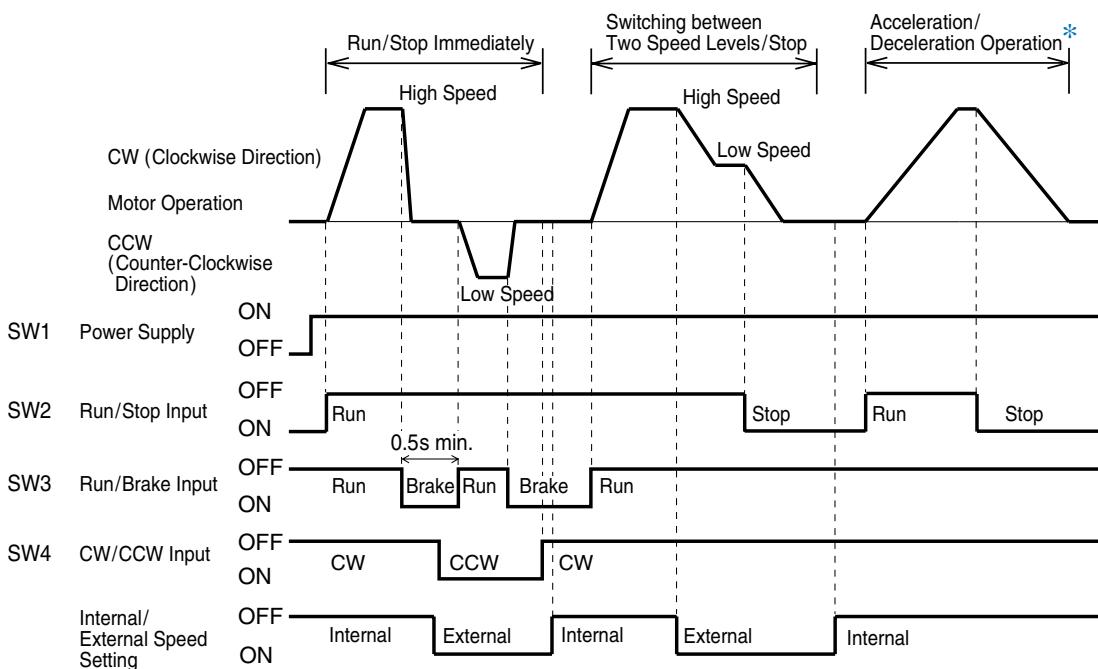
Power Supply Voltage	110/115 VAC (ES01)	220/230 VAC (ES02)
SW1	125 VAC 10 A	250 VAC 5 A
SW2, SW3		18 VDC 1 mA
SW4	125 VAC 10 A	250 VAC 5 A
R0, C0 (Surge suppressor)	$R_0=5\sim200\ \Omega$ $C_0=0.1\sim0.2\ \mu F, 200\ WV$	$R_0=5\sim200\ \Omega$ $C_0=0.1\sim0.2\ \mu F, 400\ WV$
Fuse	Product certified under the UL/CSA248-14 standard or equivalent 250 VAC 10 A	Product certified under the UL/CSA248-14 standard or equivalent 250 VAC 5 A

Precaution for wiring

- The control input terminals are not insulated from the AC power supply. Any equipment (sequencer, relay and/or switch) that will be connected to the control input terminals must have contact ratings of 18 VDC and 1 mA min.
- The length of the cable connecting the motor and speed controller should be no more than 32.8 feet (10 m).
- The length of the control cable should be no more than 6.6 feet (2 m) and as short as possible.

● Timing Chart

The timing chart below shows an example of switching between two speed levels when the high speed and low speed are selected via the internal and external speed potentiometers, respectively.



* Case where the acceleration and deceleration times are set longer by turning each potentiometer clockwise.

● Run/Brake, Stop

Setting SW2/SW3 to "Run" (OFF) causes the motor to rotate at the speed set via the speed potentiometers.

Setting SW2 to "Stop" (ON) during operation causes the motor to coast to a stop.

Setting SW3 to "Brake" (ON) during operation causes the motor to stop immediately.

The braking function (current through the motor) is only active for approximately 0.4 seconds after the Run/Brake input is turned ON. It is important to wait 0.5 seconds, or greater, prior to switching back to Run. Otherwise, damage to the speed controller may result.

Run/Stop Input	Run/Brake Input	Motor Operation
OFF	OFF	Runs
OFF	ON	Stops Immediately
ON	OFF	Coasts to a Stop*

* The slow down time set with a potentiometer is longer than the time which motor coasts to a stop, motor will stop with slow down time.

● Switching the Direction of Rotation

SW4 is used to switch the motor's direction of rotation.

When SW4 is set to CW, the motor rotates in the clockwise direction, as seen from the motor's output-shaft side.

When SW4 is set to CCW, the motor rotates in the counterclockwise direction, as seen from the motor's output-shaft side.

The rotating direction of the gear output shaft is opposite that of the motor shaft, depends on the gear ratio.

- Instant switching between forward and reverse operations is possible with a reversible motor. Connect a surge suppressor between the relay contacts. Oriental Motor also provides an optional **EPCR1201-2** CR circuit for surge suppression. →Page A-218
- For bi-directional operation of an induction motor, switch the rotating direction after the motor has come to a complete stop.

Speed Setting Methods

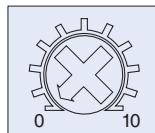
The following two methods of setting speed can be used.

Internal Speed Potentiometer

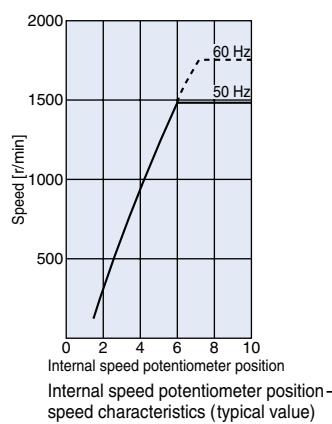
The setting range is from 90 to 1400 r/min at 50 Hz or 90 to 1600 r/min at 60 Hz. Short the speed potentiometer input terminals S4 and S5.

Turning the potentiometer clockwise will set a faster speed.

The factory setting is 0 r/min.



Internal Speed Potentiometer



Internal speed potentiometer position-speed characteristics (typical value)

External Speed Potentiometer (included)

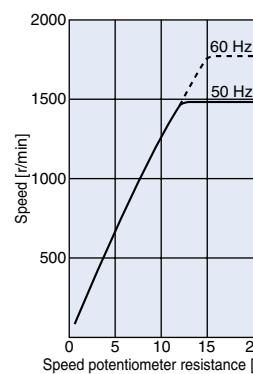
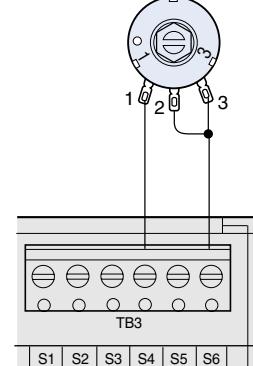
Open the speed potentiometer input terminals S4 and S5.

Before connecting, turn the dial on the external speed potentiometer counterclockwise to set the speed to 0 r/min.

Turning the dial clockwise will set a faster speed.

External Speed Potentiometer

20 kΩ 1/4 W
with a linear resistance vs.
angle curve



External speed potentiometer resistance-speed characteristics (typical value)

Note:

Do not operate multiple speed controllers with a single external speed potentiometer. Doing so may damage the speed controllers.

Acceleration and Deceleration Operation

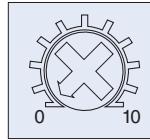
Equipment and loads are subject to large acceleration/deceleration force when starting, stopping, and changing speeds. When you want to accelerate/decelerate without any accompanying shock, the acceleration/deceleration time can be extended using the slow start/slow down function. The slow start/slow down time can be set using acceleration/deceleration time potentiometers built into the control pack. However, when the load inertia is large, the deceleration time cannot be set at a shorter time than when the motor is stopped naturally.

Acceleration

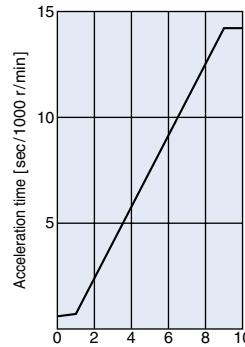
The acceleration function is actuated at start or when the speed is switched to the higher setting in a two-level speed control system.

Turning the acceleration time potentiometer clockwise will increase the set time.

The factory setting is 0 (no acceleration).



Acceleration Time Potentiometer



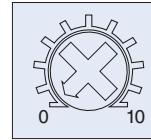
Acceleration time potentiometer position-speed characteristics (typical value)

Deceleration

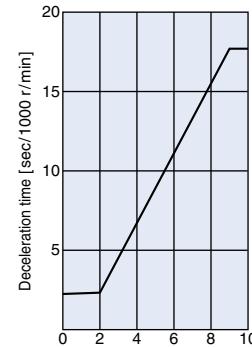
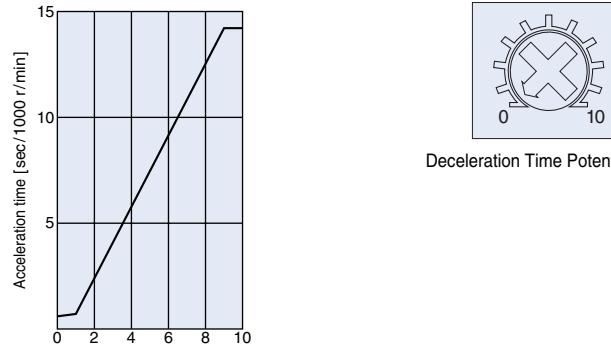
The deceleration function is actuated during natural stop or when the speed is switched to the lower setting in a two-level speed control system.

Turning the deceleration time potentiometer clockwise will increase the set time.

The factory setting is 0 (no deceleration).



Deceleration Time Potentiometer



Deceleration time potentiometer position-speed characteristics (typical value)

● Repeated Operation/Braking Cycle

When running/braking of the motor is repeated in short cycles, the rise in motor temperature will increase and the continuous-operation time will be limited.

Use the following values as a guideline:

Motor Output		Repetition Cycle
HP	W	
1/125~1/19	6~40	2 seconds min. (Running 1 second, stopping 1 second)
1/12, 1/8	60, 90	4 seconds min. (Running 2 seconds, stopping 2 seconds)

Note:

- The motor may generate heat, depending on the conditions in which it is driven. Ensure that the temperature of the motor case does not exceed 194°F (90°C).

● Braking Current

When the motor is commanded to stop immediately, the following braking current will flow. Provide an appropriate power supply by referring to these values.

Motor Output	HP	Braking Current (Peak Value) [A]	
		Single-Phase 110/115 VAC	Single-Phase 220/230 VAC
1/125	6	1.5	1.0
1/50	15	3.5	2.0
1/30	25	5.5	3.0
1/19	40	8.5	6.0
1/12	60	15.5	8.0
1/8	90	20.5	12.0

■ List of Motor and Gearhead Combinations

Model names for motor/gearhead combinations are shown below.

● Induction Motors

Output Power	Model	Motor Model	Gearhead Model
HP	W		
1/125	VSI206A- □ U	VSI206A-GV	GV2G□
	VSI206C- □ E	VSI206C-GV	
1/50	VSI315A- □ U	VSI315A-GV	GV3G□
	VSI315C- □ E	VSI315C-GV	
1/30	VSI425A- □ U	VSI425A-GV	GV4G□
	VSI425C- □ E	VSI425C-GV	
1/19	VSI540A- □ U	VSI540A-GVH	GVH5G□
	VSI540C- □ E	VSI540C-GVH	
1/12	VSI560A- □ U	VSI560A-GVH	GVH5G□
	VSI560C- □ E	VSI560C-GVH	
1/8	VSI590A- □ U	VSI590A-GVR	GVR5G□
	VSI590C- □ E	VSI590C-GVR	

- Enter the gear ratio in the box (□) with in the model name.

● Reversible Motors

Output Power	Model	Motor Model	Gearhead Model
HP	W		
1/125	VSR206A- □ U	VSR206A-GV	GV2G□
	VSR206C- □ E	VSR206C-GV	
1/50	VSR315A- □ U	VSR315A-GV	GV3G□
	VSR315C- □ E	VSR315C-GV	
1/30	VSR425A- □ U	VSR425A-GV	GV4G□
	VSR425C- □ E	VSR425C-GV	
1/19	VSR540A- □ U	VSR540A-GVH	GVH5G□
	VSR540C- □ E	VSR540C-GVH	
1/12	VSR560A- □ U	VSR560A-GVH	GVH5G□
	VSR560C- □ E	VSR560C-GVH	
1/8	VSR590A- □ U	VSR590A-GVR	GVR5G□
	VSR590C- □ E	VSR590C-GVR	

- Enter the gear ratio in the box (□) with in the model name.

AC Motor Systems US Series

The **US** Series combines a control unit and an AC speed control motor. Connection between the motor and control unit is simplified by an easy-to-use connector. The **US** Series is designed for applications where remote control of the motor speed and easy installation are required.



Gearhead shown in the photograph is sold separately.

■ Features

● Easy Connection

Control units combine the control pack, potentiometer and capacitor into one device (except 60 W and 90 W models). Operation is possible just by connecting the control unit into the power supply after connecting the motor and control unit together using the connector.

● Easy Operation

The speed can be set easily with the potentiometer on the front panel of the control unit.

● Approved by Safety Standards

The **US** Series is recognized by UL/CSA standards and conforms to EN standards. CE marking is used in accordance with the Low Voltage Directives.

■ Safety Standards and CE Marking

	Standards	Certification Body	Standards File No.	CE Marking	
Motor	UL1004 UL2111	UL	E64199 (6 W type) E64197 (15 W~90 W type)	Low Voltage Directives	
	CSA C22.2 No.100 CSA C22.2 No.77				
	EN60950	VDE	114919ÜG (6 W type) 6751ÜG (15 W~90 W type)		
	EN60034-1 EN60034-5	Conform to EN/IEC Standards			
	IEC60034-11 (15 W~90 W type)				
Control Unit	UL508	UL	E91291		
	CSA C22.2 No.14				
	EN60950 EN50178	Conform to EN/IEC Standards			

- When the system is approved under various safety standards, the model names on the motor and control unit are the approved model names.
[List of Motor and Control Unit Combinations](#) → Page B-130
- Details of Safety Standards** → Page G-2
- Single-Phase 220/230 VAC models conform to EMC directives.

The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the motor/control unit incorporated in the user's equipment.

■ Product Line

● Single-Phase 110/115 VAC

Output Power HP	W	Model Pinion Shaft	Model Round Shaft
1/125	6	US206-401U	US206-001U
1/50	15	US315-401U	US315-001U
1/30	25	US425-401U	US425-001U
1/19	40	US540-401U	US540-001U
1/12	60	US560-501U	US560-001U
1/8	90	US590-501U	US590-001U

● Single-Phase 220/230 VAC

Output Power HP	W	Model Pinion Shaft	Model Round Shaft
1/125	6	US206-402E	US206-002E
1/50	15	US315-402E	US315-002E
1/30	25	US425-402E	US425-002E
1/19	40	US540-402E	US540-002E
1/12	60	US560-502E	US560-002E
1/8	90	US590-502E	US590-002E

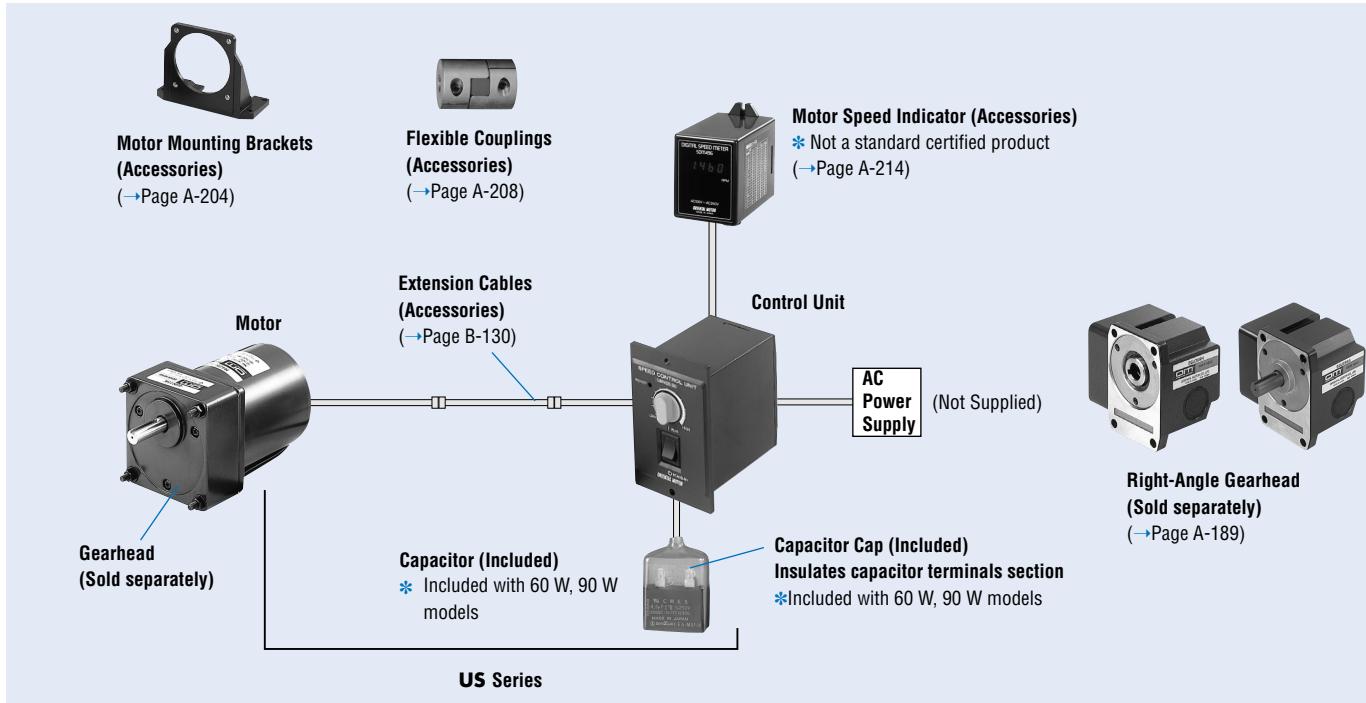
● Gearheads (Sold Separately)

Motor Model	Gearhead Model
US206 Type	2GN3KA~2GN180KA 2GN10XK (Decimal Gearhead)
US315 Type	3GN3KA~3GN180KA 3GN10XK (Decimal Gearhead)
US425 Type	4GN3KA~4GN180KA 4GN10XK (Decimal Gearhead)
US540 Type	5GN3KA~5GN180KA 5GN10XK (Decimal Gearhead)
US560, US590 Type	5GU3KA~5GU180KA 5GU10XKB (Decimal Gearhead)
US590 Type	5GU50KHA~5GU180KHA 5GU10XK (Decimal Gearhead)

● Right-Angle Gearheads (Sold Separately)

Type of Shaft	Gearhead Model
Hollow Shaft	4GN3.6RH~4GN180RH 5GN3.6RH~5GN180RH 5GU3.6RH~5GU180RH
Solid Shaft	4GN3.6RAA~4GN180RAA 5GN3RAA~5GN180RAA 5GU3RAA~5GU180RAA

■ System Configuration



The system configuration shown is an example. Other configurations are available.

■ Product Number Code

US 5 60 - 5 0 1 U

Included Capacitor
U: 110/115 VAC
E: 220/230 VAC

Voltage
1: Single-Phase 110/115 VAC
2: Single-Phase 220/230 VAC

Motor Type
O: Induction Motor (Continuous rating)

Shaft Type
0: Round Shaft

4: **GN** Pinion Shaft (for use with **GN**-type gearhead)
5: **GU** Pinion Shaft (for use with **GU**-type gearhead)

Output Power
06: 6 W 40: 40 W
15: 15 W 60: 60 W
25: 25 W 90: 90 W

Motor Frame Size
2: 2.36 in. sq. (60 mm sq.)
3: 2.76 in. sq. (70 mm sq.)
4: 3.15 in. sq. (80 mm sq.)
5: 3.54 in. sq. (90 mm sq.)

Series
US: US Series

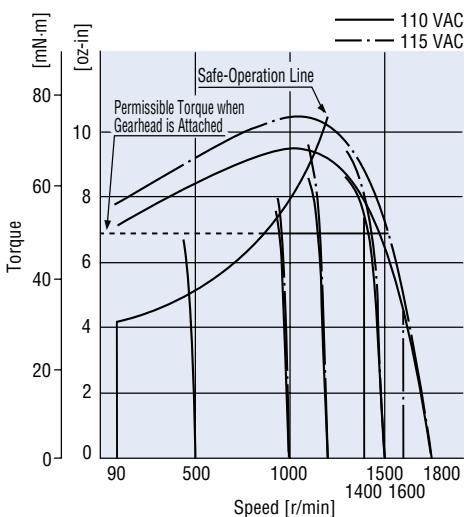
Product Number Code of the Gearheads →Page A-16

Introduction	BX	FBL II	AXU	AXH	BHF	ES	US	AC Motor Systems
	Brushless DC Motor Systems	AC Input	DC Input					

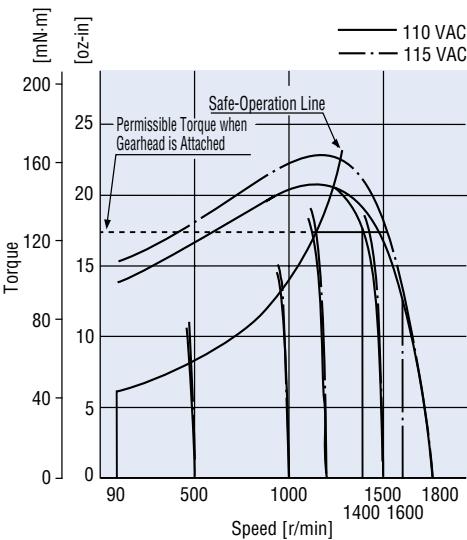
Before using a
Speed Control
System

Speed — Torque Characteristics

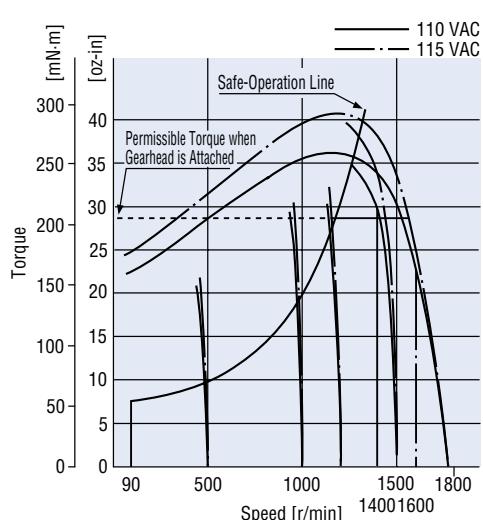
US206-401U
US206-001U



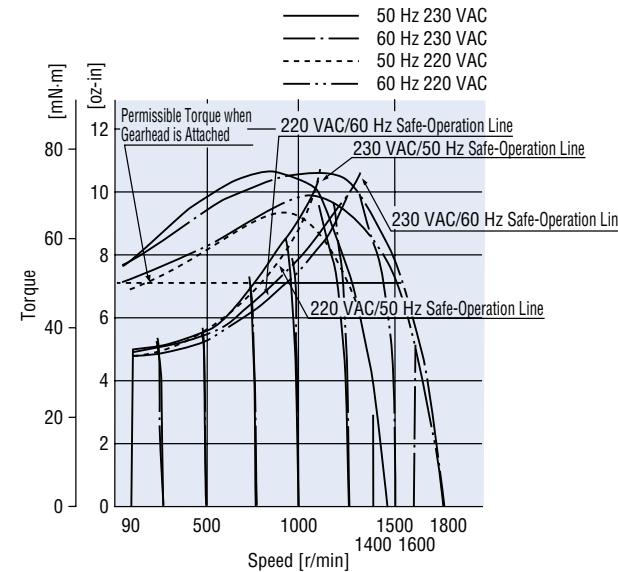
US315-401U
US315-001U



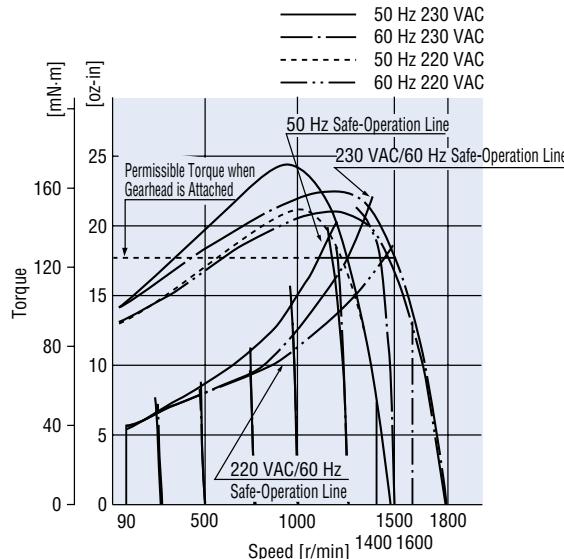
US425-401U
US425-001U



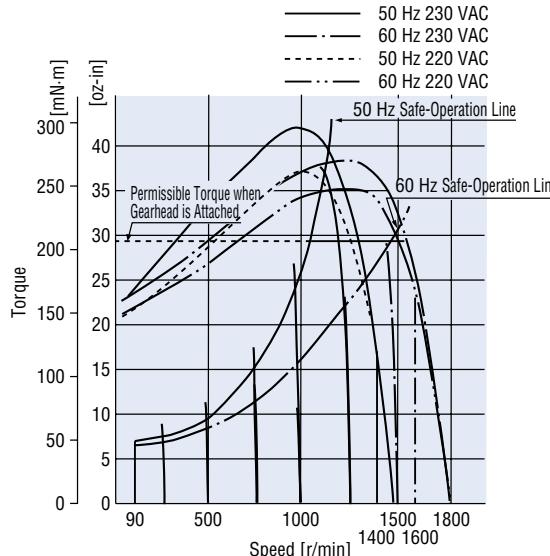
US206-402E
US206-002E

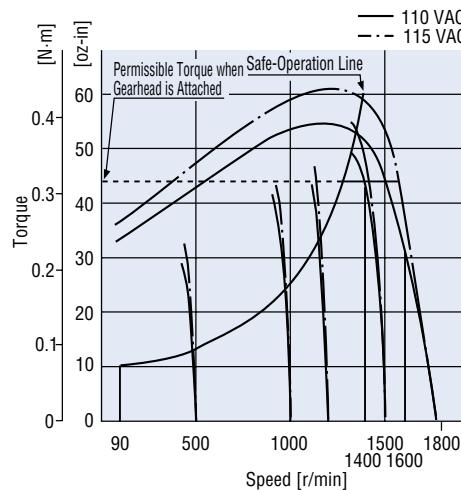
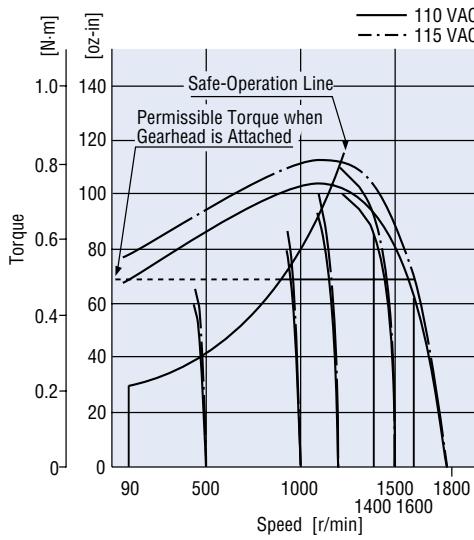
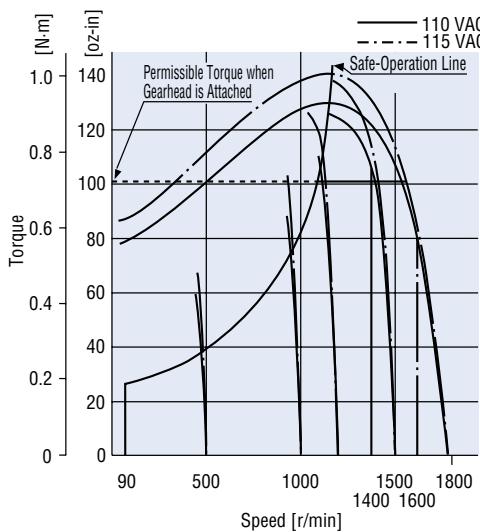
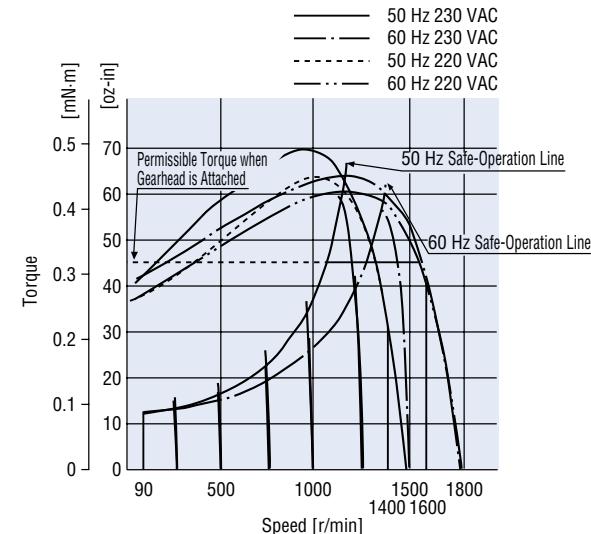
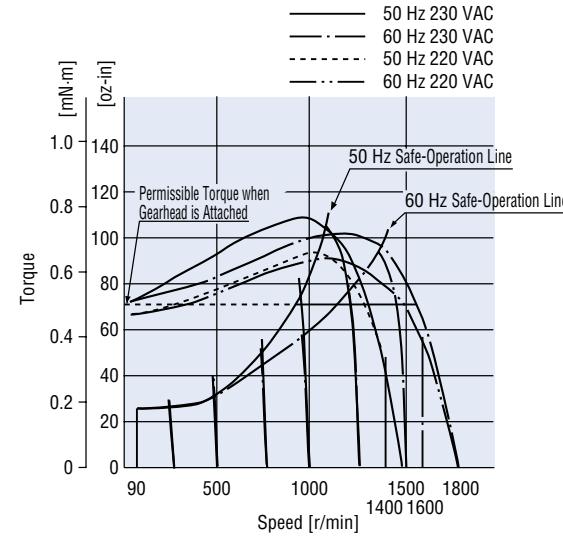
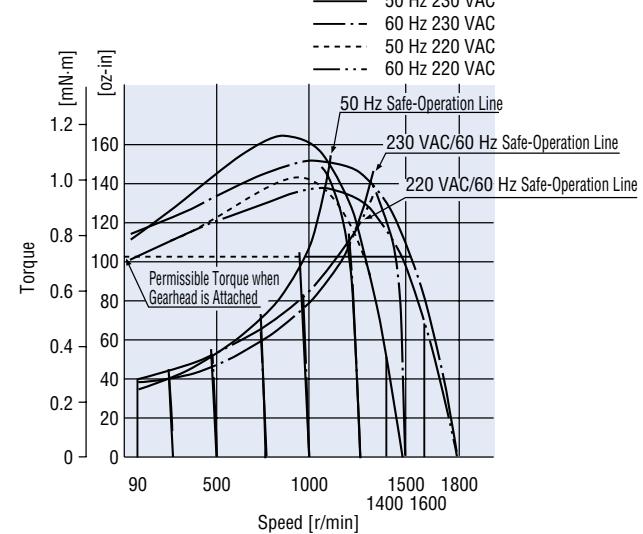


US315-402E
US315-002E



US425-402E
US425-001E



**US540-401U
US540-001U****US560-501U
US560-001U****US590-501U
US590-001U****US540-402E
US540-002E****US560-502E
US560-002E****US590-502E
US590-002E**

Dimensions

Scale 1/4, Unit = inch (mm)

Mounting screws are included with gearheads. Dimensions for screws → Page A-223

Enter the gear ratio in the box (□) within the model name.

Motor/Gearhead

US206-401U, US206-402E (Pinion Shaft Type)

Motor: USM206-401W, USM206-402W

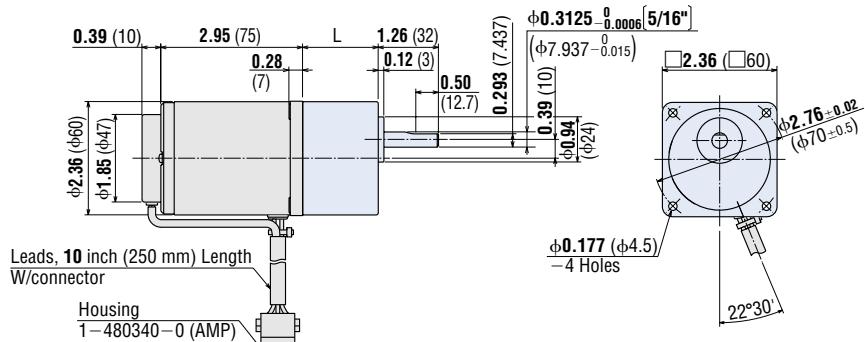
Weight: 1.76 lb. (0.8 kg)

Gearhead: **2GN□KA**

Weight: 0.88 lb. (0.4 kg)

DXF A078AU (**2GN3KA~18KA**)

A078BU (**2GN25KA~180KA**)



2GN3KA-18KA: L = 1.18 (30)

2GN25KA-180KA: L = 1.57 (40)

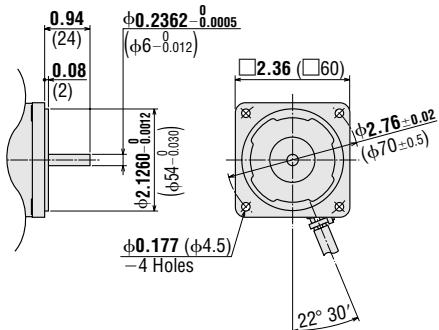
Round Shaft Type

US206-001U, US206-002E

Motor: USM206-001W, USM206-002W

Weight: 1.76 lb. (0.8 kg)

DXF A354



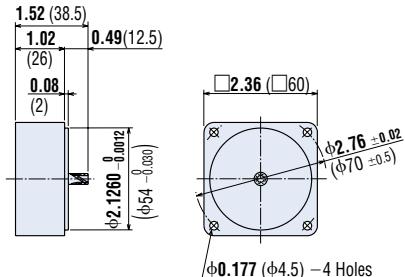
Decimal Gearhead

Can be connected to **US206GN** pinion shaft type

2GN10XK

Weight: 0.44 lb. (0.2 kg)

DXF A003



Motor/Gearhead

US315-401U, US315-402E (Pinion Shaft Type)

Motor: USM315-401W, USM315-402W

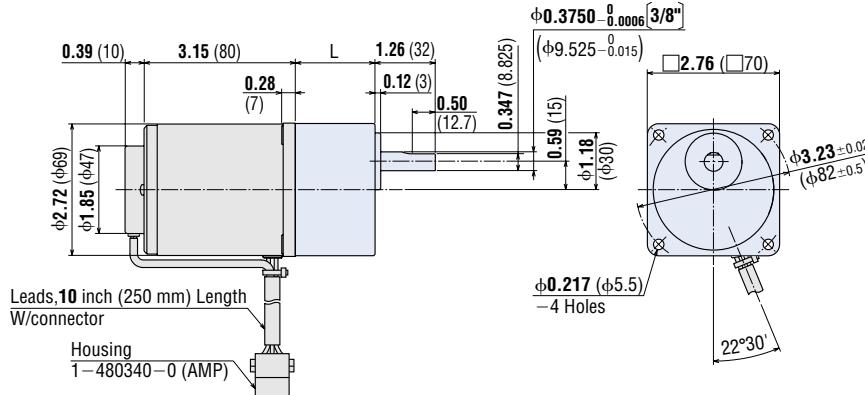
Weight: 2.6 lb. (1.2 kg)

Gearhead: **3GN□KA**

Weight: 1.21 lb. (0.55 kg)

DXF A079AU (**3GN3KA~18KA**)

A079BU (**3GN25KA~180KA**)



3GN3KA-18KA: L = 1.26 (32)

3GN25KA-180KA: L = 1.65 (42)

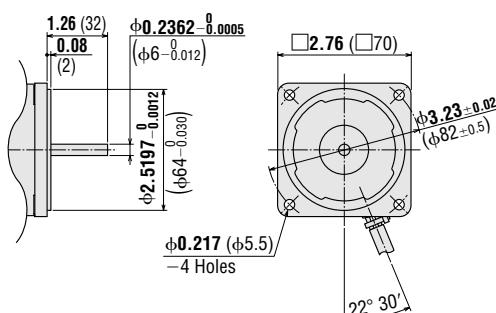
● Round Shaft Type

US315-001U, US315-002E

Motor: USM315-001W, USM315-002W

Weight: 2.6 lb. (1.2 kg)

DXF A355



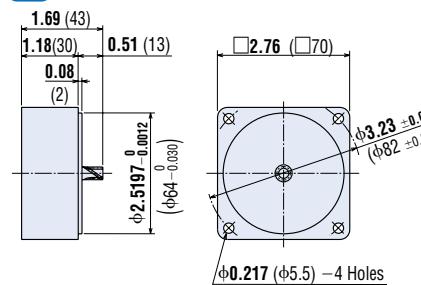
● Decimal Gearhead

Can be connected to **US315GN** pinion shaft type

3GN10XK

Weight: 0.66 lb. (0.3 kg)

DXF A009



● Motor/Gearhead

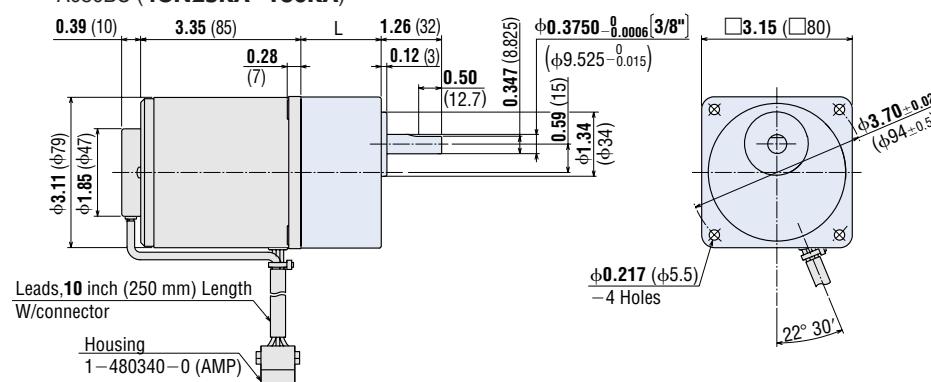
US425-401U, US425-402E (Pinion Shaft Type)

Motor: USM425-401W, USM425-402W

Weight: 3.5 lb. (1.6 kg)

DXF A080AU (**4GN3KA~18KA**)

A080BU (**4GN25KA~180KA**)



4GN3KA~18KA: L = 1.26 (32)

4GN25KA~180KA: L = 1.67 (42.5)

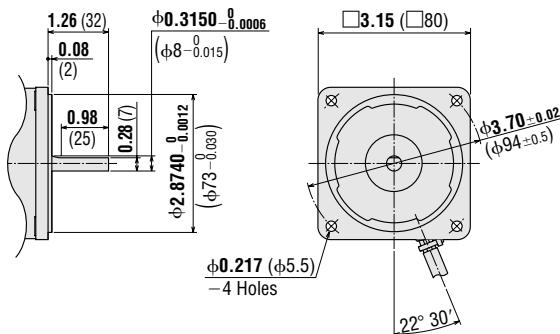
● Round Shaft Type

US425-001U, US425-002E

Motor: USM425-001W, USM425-002W

Weight: 3.5 lb. (1.6 kg)

DXF A356



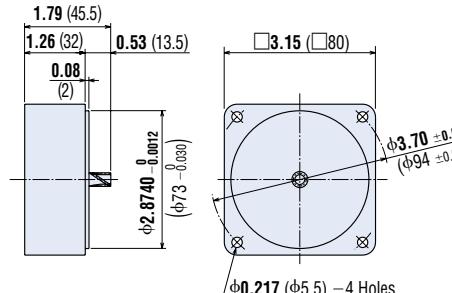
● Decimal Gearhead

Can be connected to **US425GN** pinion shaft type

4GN10XK

Weight: 0.88 lb. (0.4 kg)

DXF A013



● Motor/Gearhead

US540-401U, US540-402E (Pinion Shaft Type)

Motor: USM540-401W, USM540-402W

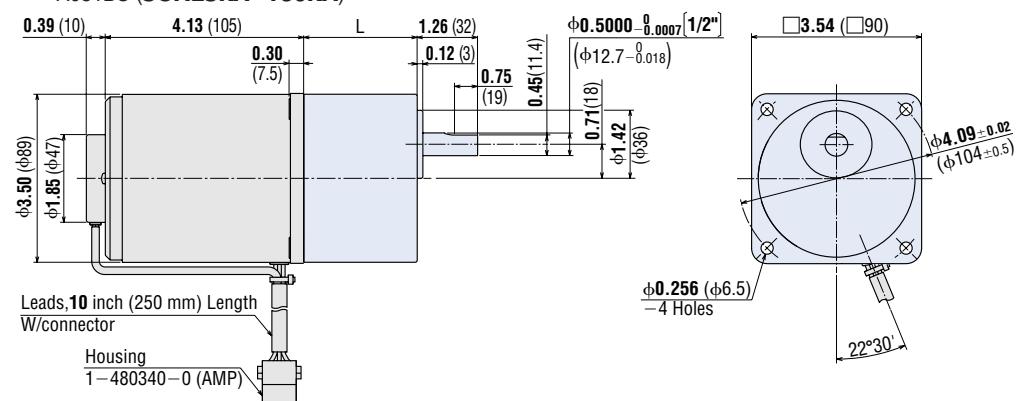
Weight: 5.7 lb. (2.6 kg)

Gearhead: **5GN□KA**

Weight: 3.3 lb. (1.5 kg)

DXF A081AU (**5GN3KA~18KA**)

A081BU (**5GN25KA~180KA**)



5GN3KA-18KA: L = 1.65 (42)
5GN25KA-180KA: L = 2.36 (60)

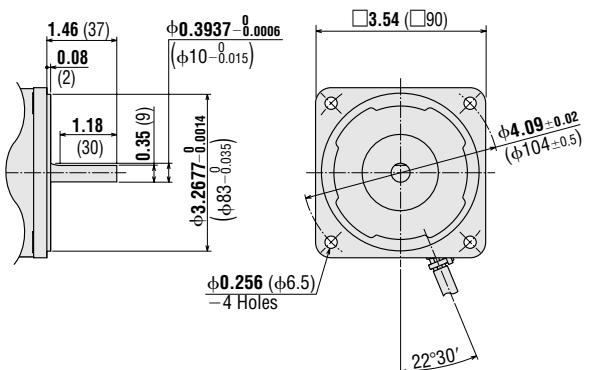
● Round Shaft Type

US540-001U, US540-002E

Motor: USM540-001W, USM540-002W

Weight: 5.7 lb. (2.6 kg)

DXF A357



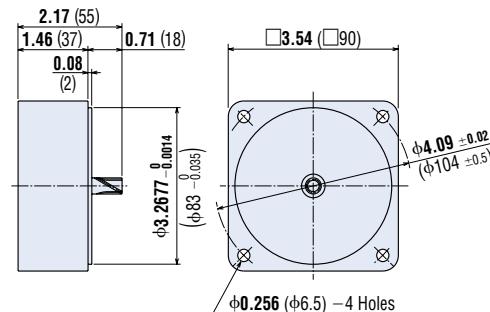
● Decimal Gearhead

Can be connected to **US540GN** pinion shaft type

5GN10XK

Weight: 1.32 lb. (0.6 kg)

DXF A022



● Motor/Gearhead

US560-501U, US560-502E (Pinion Shaft Type)

Motor: USM560-501W, USM560-502W

Weight: 6.2 lb. (2.8 kg)

DXF A082U

Gearhead: **5GU□KA**

Weight: 3.3 lb. (1.5 kg)

US590-501U, US590-502E (Pinion Shaft Type)

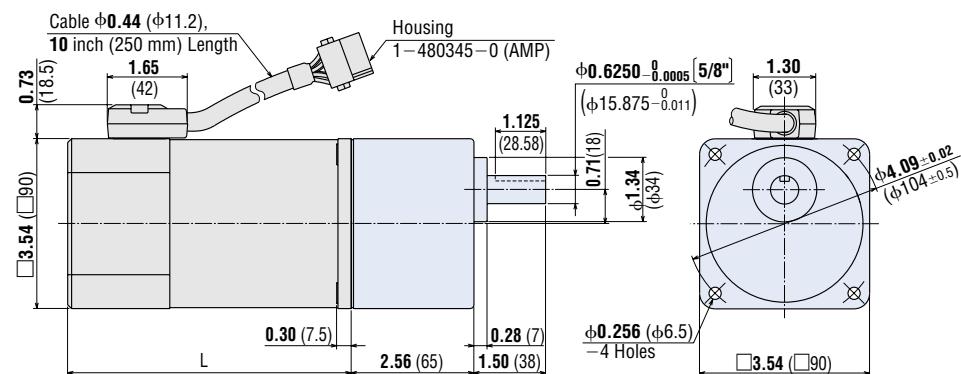
Motor: USM590-501W, USM590-502W

Weight: 7.9 lb. (3.6 kg)

DXF A083U

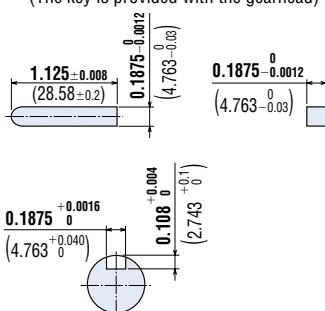
Gearhead: **5GU□KA**

Weight: 3.3 lb. (1.5 kg)



● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



Model	L inch (mm)	DXF
US560 Type	5.91 (150)	A082U
US590 Type	6.50 (165)	A083U

● Round Shaft Type

US560-001U, US560-002E

Motor: USM560-001W, USM560-002W

Weight: 6.2 lb. (2.8 kg)

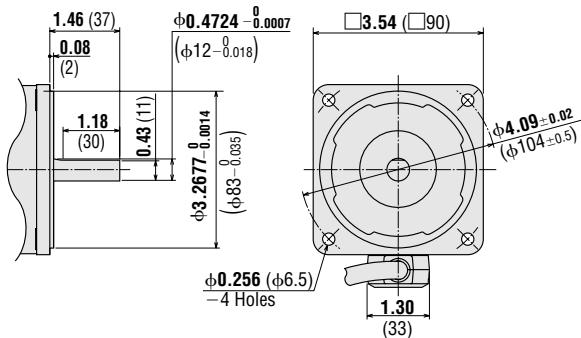
DXF A358

US590-001U, US590-002E

Motor: USM590-001W, USM590-002W

Weight: 7.9 lb. (3.6 kg)

DXF A359



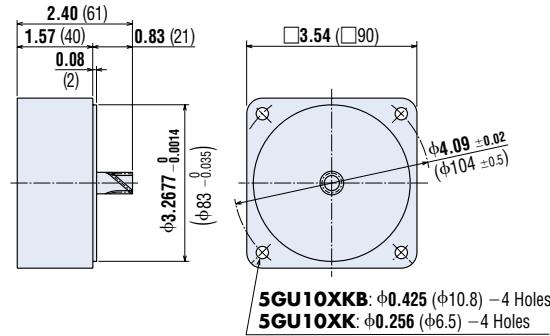
● Decimal Gearhead

Can be connected to **US560GU** and **US590GU** pinion shaft type

5GU10XKB (For **5GU□KA**), **5GU10XK** (For **5GU□KHA**)

Weight: 1.32 lb. (0.6 kg)

DXF A029



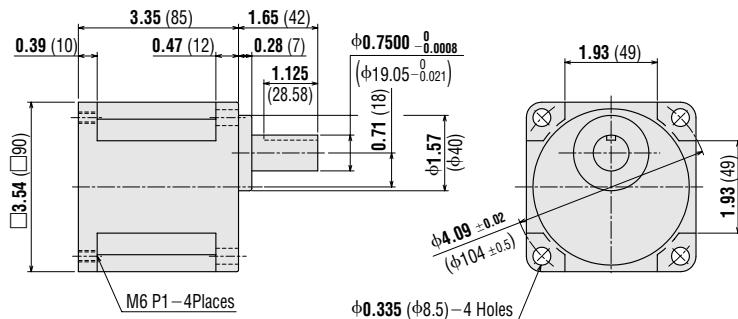
5GU10XKB: φ0.425 (10.8) - 4 Holes
5GU10XK: φ0.256 (6.5) - 4 Holes

● High-Power Gearheads

5GU□KHA

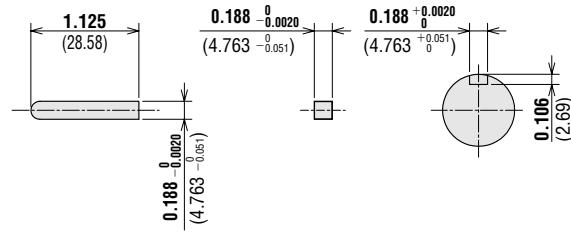
Weight: 4.2 lb. (1.9 kg)

DXF A038U



● Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead)



◆ Control Unit

For use with **US206**, **US315**, **US425** and **US540** types

USP206-1U/USP206-2E

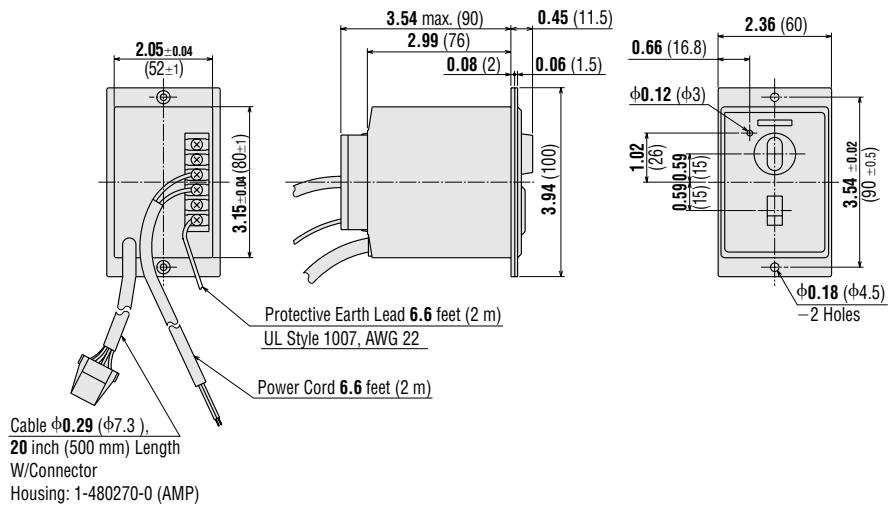
USP315-1U/USP315-2E

USP425-1U/USP425-2E

USP540-1U/USP540-2E

Weight: 0.99 lb. (0.45 kg)

DXF A817



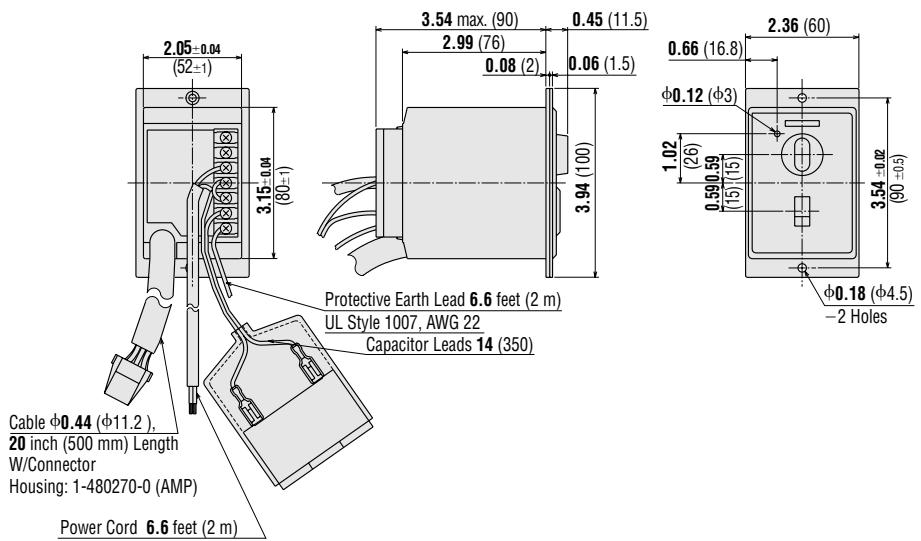
For use with **US560** and **US590** types

USP560-1U/USP560-2E

USP590-1U/USP590-2E

Weight: 1.1 lb. (0.5 kg)

DXF A818

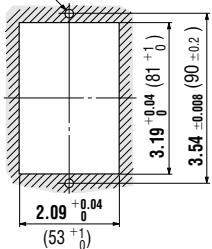


◆ Panel Cut-Out for Control Unit

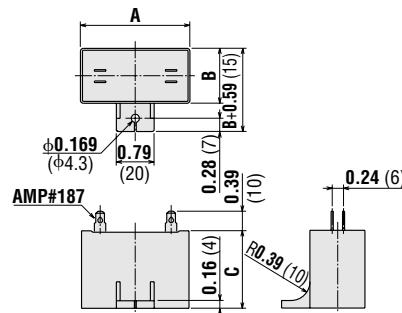
Installation Method by Cutting a Hole

φ0.18 (φ 4.5) Holes

-2 Places



● Capacitor (included with the motors)

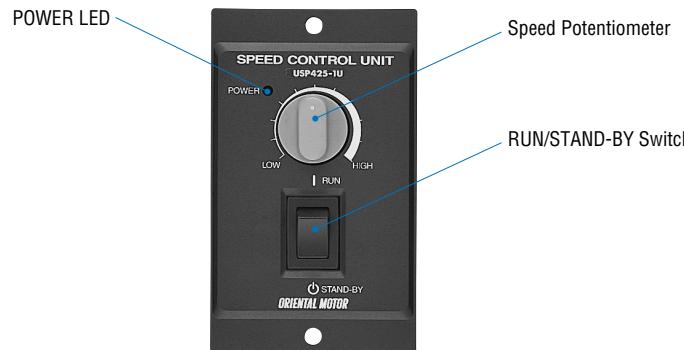


Capacitor Dimensions Unit = inch (mm)

Package Model	Capacitor Model	A	B	C	Weight oz (g)
US560-□O1U	CH180CFAUL	2.28 (58)	0.93 (23.5)	1.46 (37)	2.5 (70)
US560-□O2E	CH40BFAUL	2.28 (58)	0.93 (23.5)	1.46 (37)	2.5 (70)
US590-□O1U	CH200CFAUL	2.28 (58)	1.14 (29)	1.61 (41)	3.4 (95)
US590-□O2E	CH60BFAUL	2.28 (58)	1.14 (29)	1.61 (41)	3.0 (85)

- If you need to order a capacitor without a motor, add "-C" to the capacitor model name shown. A capacitor cap is included with a capacitor.

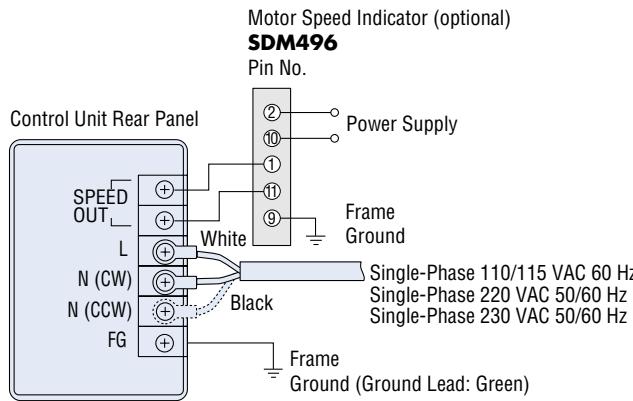
■ Connection and Operation



● Connection Diagrams

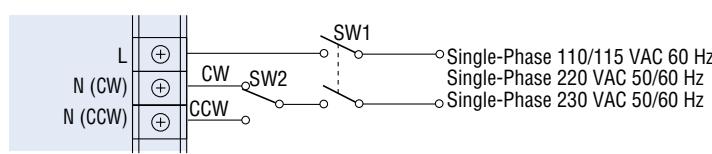
US206, US315, US425, US540 types

Uni-directional Rotation:



In the diagrams above, the motor shaft rotates in the clockwise direction. When changed to the dotted line [N (CCW)] position, the motor shaft rotates in the counterclockwise direction.

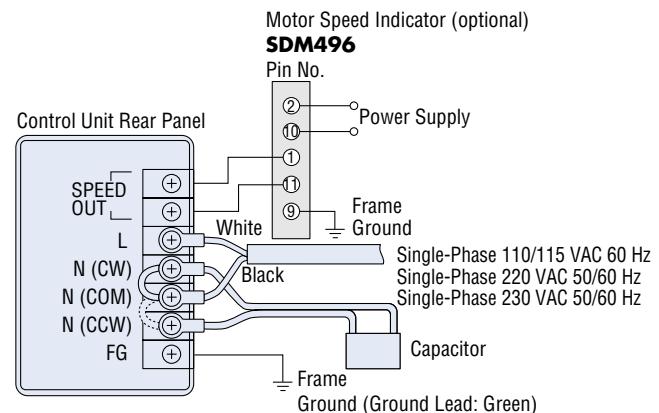
Bi-directional Rotation:



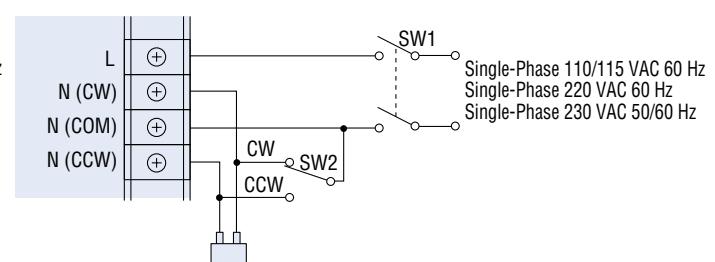
Switch Specifications: 250 VAC, Inductive Load, 5 A min.

US560, US590 types

Uni-directional Rotation:



Bi-directional Rotation:

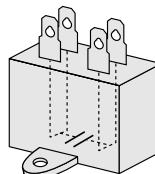


Switch Specifications: 250 VAC, Inductive Load, 5 A min.

- If an extension between the motor and control unit is required, an extension cable can be used (sold separately). Using the longest cord, the distance can be extended up to 15.7 feet (4.75 m). →Page B-130

● Inner Connection Diagram for 4-Terminal Capacitor

Terminals of the capacitor are connected as shown in the figure. For lead wire connection, use one lead wire per terminal.



● Operation Method

There is a difference in operation method between the **US206, US315, US425, US540** types and the **US560, US590** types.

US206, US315, US425 and US540 types

Connect the motor lead wire connectors to the control unit. Then connect the power cord to the power supply. When the RUN/STAND-BY switch of the control unit is switched to RUN, the motor rotates in the clockwise (CW) direction as seen from the motor shaft.

(Control units are set for clockwise rotation at shipment. The direction of rotation for the gearhead output shaft may be the reverse of the direction of the motor shaft depending on the gear ratio.)

US560 and US590 types

Connect the control unit and the motor, and attach the capacitor wire leading from the control unit to the capacitor. Next, plug in the power supply cord into an AC power supply. When the RUN/STAND-BY switch located on the control unit is switched to RUN, the motor will rotate in the direction set by the connection of the capacitor.

(Control units are set for clockwise rotation at shipment. The direction of rotation for the gearhead output shaft may be the reverse of the direction of the motor shaft depending on the gear ratio.)

● Changing Speed

When the potentiometer located on the front of the control unit is turned in a clockwise direction, motor speed increases; when turned in the counter clockwise direction, motor speed decreases. Motor speed can be set and adjusted over a range of 90 r/min-1600 r/min.

● Stopping

When the RUN/STAND-BY switch on the control unit is set to STAND-BY, the motor stops. This switch is not a power ON/OFF switch. If the motor is to be stopped for a long time, a separate power ON/OFF switch should be installed.

● Changing the Direction of Rotation **US206, US315, US425 and US540 types**

(Capacitor is included in the control unit.)

Uni-directional Rotation

When the direction of motor rotation needs to be reversed for reasons relating to transmission mechanisms such as gearheads, change the terminal used for attaching the power cord, located at the back of control unit, from terminal N (CW) to terminal N (CCW). The power cord connections are located at terminals L and N (CW) when shipped. See the diagram on the previous page.

(This should always be done with the power OFF.)

Bi-directional Rotation

Install an additional power switch (SW1) and CW/CCW switch (SW2) as shown on previous page, and use these switches to change the direction of rotation. (Motor cannot be reversed instantaneously. Turn SW1 off and wait until the motor has come to a complete stop before switching SW2.) See the diagram on the previous page.

US560 and US590 types

(Connection of the included capacitor is necessary.)

Uni-directional Rotation

When the direction of motor rotation needs to be reversed, change the terminal used for attaching the power cord, located at the back of control unit, from terminals N (CW)-N (COM) to terminals N (COM)-N (CCW). The power cord connections are located at terminals N (CW)-N (COM) when shipped. See the diagram on the previous page.

(This should always be done with the power OFF.)

Bi-directional Rotation

Install an additional power switch (SW1) and CW/CCW switch (SW2) as shown on the previous page, and use these switches to change the direction of rotation. (Motor cannot be reversed instantaneously. Turn SW1 off and wait until the motor has come to a complete stop before switching SW2.) See the diagram on the previous page.

■ List of Motor and Control Unit Combinations

Model numbers for motor and control unit combinations are shown below.

● Single-Phase 110/115 VAC

Output Power HP W		Package Model	Motor Model	Control Unit Model
1/125	6	US206-401U	USM206-401W	USP206-1U
		US206-001U	USM206-001W	
1/50	15	US315-401U	USM315-401W	USP315-1U
		US315-001U	USM315-001W	
1/30	25	US425-401U	USM425-401W	USP425-1U
		US425-001U	USM425-001W	
1/19	40	US540-401U	USM540-401W	USP540-1U
		US540-001U	USM540-001W	
1/12	60	US560-501U	USM560-501W	USP560-1U
		US560-001U	USM560-001W	
1/8	90	US590-501U	USM590-501W	USP590-1U
		US590-001U	USM590-001W	

● Single-Phase 220/230 VAC

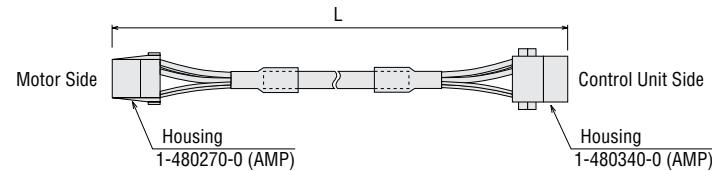
Output Power HP W		Package Model	Motor Model	Control Unit Model
1/125	6	US206-402E	USM206-402W	USP206-2E
		US206-002E	USM206-002W	
1/50	15	US315-402E	USM315-402W	USP315-2E
		US315-002E	USM315-002W	
1/30	25	US425-402E	USM425-402W	USP425-2E
		US425-002E	USM425-002W	
1/19	40	US540-402E	USM540-402W	USP540-2E
		US540-002E	USM540-002W	
1/12	60	US560-502E	USM560-502W	USP560-2E
		US560-002E	USM560-002W	
1/8	90	US590-502E	USM590-502W	USP590-2E
		US590-002E	USM590-002W	

■ Extension Cable (Sold separately)

When installing the motor and control unit in different locations, an extension cable can be used (sold separately). This enables remote operation at a distance of up to 15.7 feet. (4.75 m).

● Applicable Products: **US206, US315, US425, US540**

Model	Length: L ft. (m)
CC01SS052	3.3 (1)
CC02SS052	6.6 (2)
CC03SS052	9.8 (3)
CC04SS052	13.1 (4)



● Applicable Products: **US560, US590**

Model	Length: L ft. (m)
CC01SS2	3.3 (1)
CC02SS2	6.6 (2)
CC03SS2	9.8 (3)
CC04SS2	13.1 (4)

